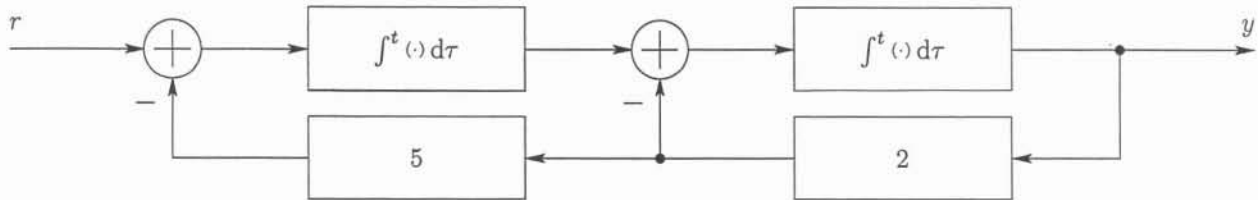


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1. Determine the system equation relating the output  $y$  to the input  $r$  for the following block diagram. The final expression should contain derivative terms and no integral terms. (20pts)



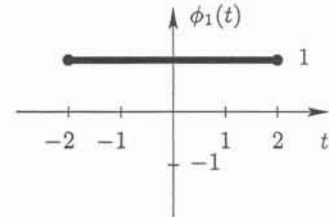
2. Consider the unit-pulse function  $p$ , where

$$p(t) = \begin{cases} 0, & \text{if } -2 \leq t \leq -1; \\ 1, & \text{if } -1 < t < 1; \\ 0, & \text{if } 1 \leq t \leq 2. \end{cases}$$

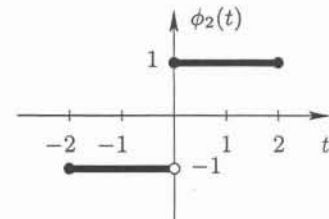
Determine the trigonometric fourier series expansion of  $p$  for  $-2 \leq t \leq 2$ . Simplify the expression as much as possible. (25pts)

3. Consider the following functions,  $\phi_1$ ,  $\phi_2$ , and  $\phi_3$ .

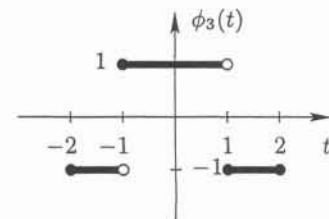
$$\phi_1(t) = 1 \text{ for } -2 \leq t \leq 2.$$



$$\phi_2(t) = \begin{cases} -1, & \text{if } -2 \leq t < 0; \\ 1, & \text{if } 0 \leq t \leq 2. \end{cases}$$



$$\phi_3(t) = \begin{cases} -1, & \text{if } -2 \leq t < -1; \\ 1, & \text{if } -1 \leq t < 1; \\ -1, & \text{if } 1 \leq t \leq 2. \end{cases}$$



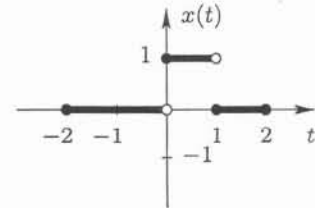
(a) Verify that  $\phi_i$  for  $i = 1, 2, 3$  are orthogonal with respect to the inner product

$$\langle f, g \rangle = \int_{-2}^2 f(t)g(t) dt.$$

(05pts)

(b) Find and plot the best representation of the function  $x$ , where

$$x(t) = \begin{cases} 0, & \text{if } -2 \leq t < 0; \\ 1, & \text{if } 0 \leq t < 1; \\ 0, & \text{if } 1 \leq t \leq 2. \end{cases}$$



as a linear combination of  $\phi_i$  for  $i = 1, 2, 3$ , such that the error based on the associated norm

$$\|f\| = \left[ \int_{-2}^2 (f(t))^2 dt \right]^{1/2},$$

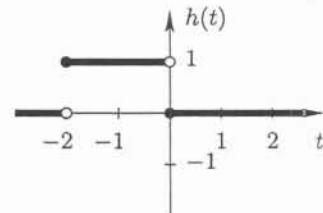
is minimized.

(25pts)

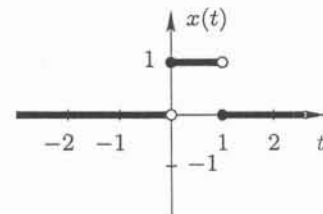
4. For the following functions,  $h$  and  $x$ , determine and plot the convolution function  $(h * x)$ .

(25pts)

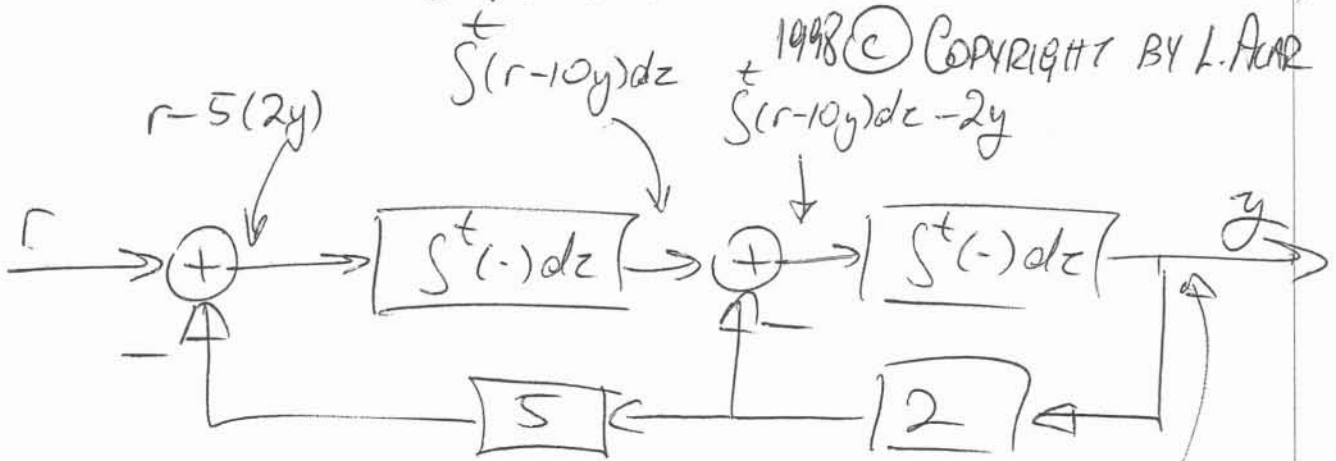
$$h(t) = \begin{cases} 1, & \text{if } -2 \leq t < 0; \\ 0, & \text{elsewhere.} \end{cases}$$



$$x(t) = \begin{cases} 1, & \text{if } 0 \leq t < 1; \\ 0, & \text{elsewhere.} \end{cases}$$



#1



$$\int^t \left[ \int^{\infty} (r - 10y) dz - 2y \right] d\tau$$

$$y = \int^t \left[ \int^{\infty} (r - 10y) dz - 2y \right] d\tau$$

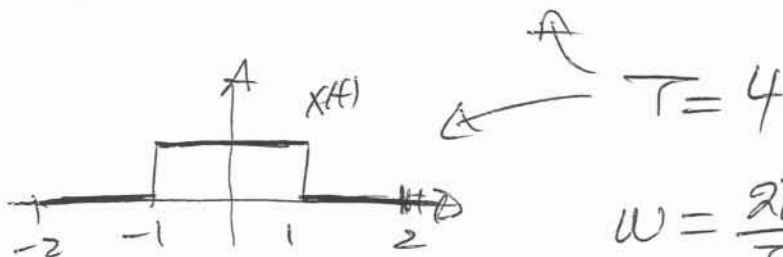
$$\dot{y} = \int^t (r - 10y) dz - 2y$$

$$\ddot{y} = (r - 10y) - 2\dot{y}$$

$$\ddot{y} + 2\dot{y} + 10y = r$$

#2

$$x(t) = \begin{cases} 0 & -2 \leq t \leq -1 \\ 1 & -1 < t < 1 \\ 0 & 1 \leq t \leq 2 \end{cases}$$



$$\omega = \frac{2\pi}{T} = \frac{\pi}{2}$$

$$x(t) = \frac{a_0}{2} + \sum_{n=1}^{\infty} \{ a_n \cos(n\omega t) + b_n \sin(n\omega t) \}$$

$$a_n = \frac{\langle x(t), \cos(n\omega t) \rangle}{\langle \cos(n\omega t), \cos(n\omega t) \rangle} = \frac{2}{T} \int_T x(t) \cos(n\omega t) dt$$

$$b_n = \frac{\langle x(t), \sin(n\omega t) \rangle}{\langle \sin(n\omega t), \sin(n\omega t) \rangle} = \frac{2}{T} \int_T x(t) \sin(n\omega t) dt$$

$$a_n = \frac{2}{4} \int_{-2}^2 x(t) \cos\left(\frac{\pi}{2} n t\right) dt$$

$$= \frac{1}{2} \int_{-1}^1 \cos\left(\frac{\pi}{2} n t\right) dt$$

$$= \frac{1}{2} \left[ \frac{1}{\pi/2 n} \sin\left(\frac{\pi}{2} n t\right) \right]_{t=-1}^1, \quad n \neq 0$$

$$= \frac{2}{\pi n} \sin\left(\frac{\pi}{2} n\right), \quad n \neq 0$$

$$a_0 = \frac{1}{2} \int_{-1}^1 dt = 1$$

$$b_n = \frac{2}{4} \int_{-2}^2 x(t) \sin\left(\frac{\pi}{2} n t\right) dt$$

$$= \frac{1}{2} \int_{-1}^1 \sin\left(\frac{\pi}{2} n t\right) dt$$

$$= \frac{1}{2} \left[ -\frac{1}{\frac{\pi}{2} n} \cos\left(\frac{\pi}{2} n t\right) \right]_{t=-1}^1, \quad n \neq 0$$

$$= 0$$

$$x(t) = \frac{1}{2} + \sum_{n=1}^{\infty} \frac{2}{\pi n} \sin\left(\frac{\pi}{2} n\right) \cos\left(\frac{\pi}{2} n t\right)$$

Note: for  $n=4k$ ,  $\frac{2}{\pi 4k} \sin\left(\frac{\pi}{2} 4k\right) = \frac{1}{2\pi k} \sin(2\pi k) = 0$

$$\begin{aligned} n=4k+1, \quad \frac{2}{\pi(4k+1)} \sin\left(\frac{\pi}{2}(4k+1)\right) &= \frac{2}{\pi(4k+1)} \sin\left(2\pi k + \frac{\pi}{2}\right) \\ &= \frac{2}{\pi(4k+1)} \end{aligned}$$

$$n=4k+2, \quad \frac{2}{\pi(4k+2)} \sin\left(\frac{\pi}{2}(4k+2)\right) = 0$$

$$n=4k+3, \quad \frac{2}{\pi(4k+3)} \sin\left(\frac{\pi}{2}(4k+3)\right) = -\frac{2}{\pi(4k+3)}$$

$$x(t) = 1 + \sum_{k=0}^{\infty} \left[ \frac{2}{\pi(4k+1)} \cos\left(\frac{\pi}{2}(4k+1)t\right) - \frac{2}{\pi(4k+3)} \cos\left(\frac{\pi}{2}(4k+3)t\right) \right]$$

#3

$$\phi_1(t) = 1, \quad -2 \leq t \leq 2$$

$$\phi_2(t) = \begin{cases} -1, & -2 \leq t < 0 \\ 1, & 0 \leq t \leq 2 \end{cases}$$

$$\phi_3(t) = \begin{cases} -1, & -2 \leq t < -1 \\ 1, & -1 \leq t < 1 \\ -1, & 1 \leq t \leq 2 \end{cases}$$

$$\begin{aligned} \langle \phi_1, \phi_2 \rangle &= \int_{-2}^0 (1)(-1) dt + \int_0^2 (1)(1) dt \\ &= -2 + 2 = 0 \end{aligned}$$

$$\begin{aligned} \langle \phi_1, \phi_3 \rangle &= \int_{-2}^{-1} (1)(-1) dt + \int_{-1}^1 (1)(1) dt + \int_1^2 (1)(-1) dt \\ &= -1 + 2 + (-1) = 0 \end{aligned}$$

$$\begin{aligned} \langle \phi_2, \phi_3 \rangle &= \int_{-2}^{-1} (-1)(-1) dt + \int_{-1}^0 (-1)(1) dt \\ &\quad + \int_0^1 (1)(1) dt + \int_1^2 (1)(-1) dt \\ &= 1 - 1 + 1 - 1 = 0 \end{aligned}$$

So  $\phi_1, \phi_2, \phi_3$  are orthogonal

$$b_{11} \quad x(t) = \begin{cases} 0 & -2 < t < 0 \\ 1 & 0 \leq t < 1 \\ 0 & 1 \leq t \leq 2 \end{cases}$$

best approx. of  $x(t)$  as a linear comb. of  $\phi_i(t)$   
is with the Fourier coefficients

$$x(t) = k_1 \phi_1(t) + k_2 \phi_2(t) + k_3 \phi_3(t)$$

$$k_1 = \frac{\langle x(t), \phi_1(t) \rangle}{\langle \phi_1(t), \phi_1(t) \rangle}$$

$$\langle x(t), \phi_1(t) \rangle = \int_0^1 (1)(1) dt = 1$$

$$\langle \phi_1(t), \phi_1(t) \rangle = \int_{-2}^2 (1)(1) dt = 4$$

$$\Rightarrow k_1 = \frac{1}{4}$$

$$k_2 = \frac{\langle x(t), \phi_2(t) \rangle}{\langle \phi_2(t), \phi_2(t) \rangle}$$

$$\langle x(t), \phi_2(t) \rangle = \int_0^1 (1)(1) dt = 1$$

$$\langle \phi_2(t), \phi_2(t) \rangle = \int_{-2}^2 (1)(1) dt + \int_0^2 (1)(1) dt \quad 2+2 = 4$$

$$\Rightarrow k_2 = \frac{1}{4}$$

$$k_3 = \frac{\langle x(t), \phi_3(t) \rangle}{\langle \phi_3(t), \phi_3(t) \rangle}$$

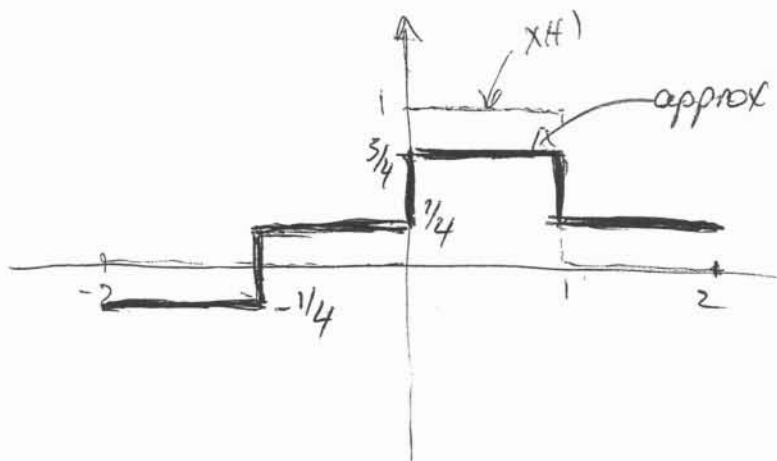
$$\langle x(t), \phi_3(t) \rangle = \int_{-1}^1 (1)(1) dt = 1$$

$$\begin{aligned} \langle \phi_3(t), \phi_3(t) \rangle &= \int_{-2}^{-1} (-1)(-1) dt + \int_{-1}^1 (1)(1) dt + \int_1^2 (-1)(-1) dt \\ &= 1 + 2 + 1 = 4 \end{aligned}$$

$$\Rightarrow k_3 = \frac{1}{4}$$

$$x(t) \approx \frac{1}{4} (\phi_1(t) + \phi_2(t) + \phi_3(t))$$

$$\approx \begin{cases} \frac{1}{4} (1 + (-1) + (-1)) = -\frac{1}{4}, & -2 \leq t < -1 \\ \frac{1}{4} (1 + (-1) + 1) = \frac{1}{4}, & -1 \leq t < 0 \\ \frac{1}{4} (1 + 1 + 1) = \frac{3}{4}, & 0 \leq t < 1 \\ \frac{1}{4} (1 + 1 + (-1)) = \frac{1}{4}, & 1 \leq t \leq 2 \end{cases}$$

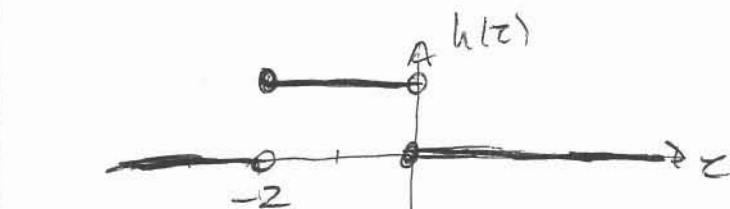




#4

$$h(t) = \begin{cases} 1, & -2 \leq t < 0 \\ 0, & \text{elsewhere} \end{cases}$$

$$x(t) = \begin{cases} 1, & 0 \leq t < 1 \\ 0, & \text{elsewhere} \end{cases}$$



$$(h*x)(t) = 0$$

$$t \leq -2$$



$$(h*x)(t) = \int_{-2}^t (1)(1) dz = t + 2$$

$$\begin{aligned} t-1 &\leq -2 \leq t \\ -1 &\leq -2-t \leq 0 \\ 1 &\leq -t \leq 2 \\ -2 &\leq t \leq -1 \end{aligned}$$

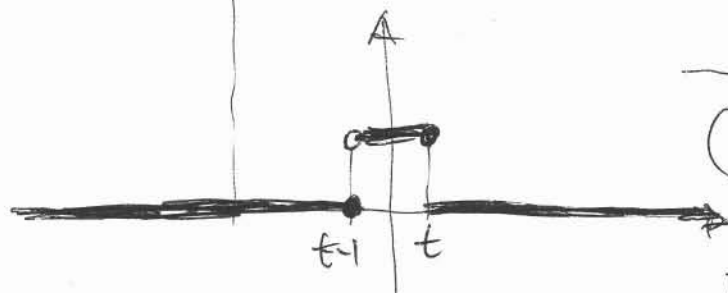


$$\begin{aligned} (h*x)(t) &= \int_{t-1}^0 (1)(1) dz \\ &= t - (t-1) = 1 \end{aligned}$$

$$t-1 \geq -2, t \geq -1$$

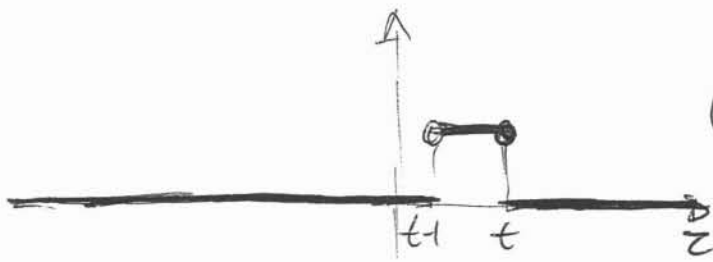
$$t \leq 0$$

$$-1 \leq t \leq 0$$



$$(h*x)(t) = \int_{t-1}^0 (1)(1) dt = -t + 1$$

$$\begin{aligned} t-1 &\leq 0 \leq t \\ -1 &\leq -t \leq 0 \\ 0 &\leq t \leq 1 \end{aligned}$$



$$(h*x)(t) = 0$$

$$0 \leq t < -1$$

$$1 \leq t$$

$$(h*x)(t) = \begin{cases} 0, & t \leq -2 \\ t+2, & -2 \leq t \leq -1 \\ 1, & -1 \leq t \leq 0 \\ -t+1, & 0 \leq t \leq 1 \\ 0, & 1 \leq t \end{cases}$$

$$A(h*x)(t)$$

