Name: (1 pt.)

Spring 2005

This is a closed-book examination. You will have 55 minutes to complete your solutions.

1.(20 pts.) Let  $\mathbf{u} \sim (1, -1, 1, -1)$  and  $\mathbf{v} \sim (1, 1, -1, 1)$  be vectors in  $\mathbf{E}^4$ . Compute:

- (a)  $\mathbf{u} \cdot \mathbf{v}$
- (b) the angle between  $\mathbf{u}$  and  $\mathbf{v}$
- (c) uv(w).

2.(20 pts.) First simplify and then carry out explicitly any implied summations in three-dimensional space:

- (a)  $\delta_i^i$
- (b)  $\delta_i^3 \delta_k^j v^k$  (c)  $\varepsilon_{i2k} \delta_n^i v^k$

3.(20 pts.) Define the phrase "T is a second order tensor on  $E^3$ " and give an example of such a tensor. Show that your example satisfies the definition of a second order tensor.

4.(20 pts.) Let x, y denote Cartesian coordinates in  $\mathbf{E}^2$  and consider the u, v coordinate system in  $\mathbf{E}^2$ defined by  $x = u^2 + v^2$ ,  $y = u^2 - v^2$ . Suppose that a second order tensor T in  $E^2$  has contravariant components

in the u, v coordinate system at the point where u = 2, v = 1. Find the component  $T^{12}$  of **T** in the Cartesian coordinate system at this point.

5.(20 pts.) Let  $u^1, u^2, u^3$  be a (general) coordinate system in  $\mathbf{E}^3$ . For this coordinate system, define:

- (a) the cellar (covariant) base vectors;
- (b) the reciprocal base vectors;
- (c) the Christoffel symbols (of the second kind).

Also, (d) write Newton's second law  $\mathbf{f} = m\mathbf{a}$  for the motion of a point-mass in the  $u^1, u^2, u^3$  coordinate system.

Bonus. (20 pts.) Let  $C: x^{i}(u)$  (i=1,2,3) be a smooth curve in  $\mathbf{E}^{3}$  in a general coordinate system  $x^1, x^2, x^3$  for  $\mathbf{E}^3$ . Define

$$V(i) = \frac{dx^i}{du} \quad (i = 1, 2, 3)$$

and

$$A(i) = \frac{d^2x^i}{du^2}$$
 (i = 1, 2, 3)

in the  $x^1, x^2, x^3$  coordinate system.

- (a) Determine whether V(1), V(2), V(3) form the components of a vector (first order tensor) in  $\mathbb{E}^3$ . Give reasons for your answer.
- (b) Determine whether A(1), A(2), A(3) form the components of a vector (first order tensor) in  $\mathbb{E}^3$ . Give reasons for your answer

## Math 322 Midterm Exam

The Math 322 midterm exam on Friday, March 4 will:

- 1. cover material in Chapters I, II, and III of Simmonds;
- 2. be a closed-book examination;
- 3. emphasize definitions, examples, important relations, and straightforward calculations.

Here are some sample midterm exam problems to help you understand the types of questions I expect you to be able to answer.

- 1. Let  $\mathbf{u} \sim (2,1,-2)$ ,  $\mathbf{v} \sim (3,-6,2)$ , and  $\mathbf{w} \sim (4,1,7)$  be vectors in  $\mathbf{E}^3$ . Compute:
  - (b) the angle between  $\mathbf{u}$  and  $\mathbf{v}$  (c)  $\mathbf{u} \times \mathbf{v}$ (d) uv(w).

Also, (e) determine whether  $\{u, v, w\}$  forms a basis for  $E^3$ .

- 2. First simplify and then carry out explicitly any implied summations in three-dimensional space:

- (a)  $\delta_j^i v^j u_i$  (b)  $\delta_j^2 \delta_k^j v^k$  (c)  $\delta_j^3 \delta_1^j$  (d)  $\varepsilon_{i3k} \delta_p^i v^k$
- 3. Define the phrase "T is a second order tensor on  $E^3$ " and give an example of such a tensor. Show that your example satisfies the definition of a second order tensor.
- 4. Consider the polar coordinate system  $(r, \theta)$  in  $\mathbf{E}^2$  defined by  $x = r\cos(\theta)$ ,  $y = r\sin(\theta)$ . Suppose that a second order tensor T in  $E^2$  has contravariant components

in the polar coordinate system at the point where r=1,  $\theta=\pi/4$ . Find the component  $T^{21}$  of **T** in the Cartesian coordinate system at this point.

- 5. Let  $\mathbf{x} = x(t)\mathbf{e}_x + y(t)\mathbf{e}_y + z(t)\mathbf{e}_z$  be a parametric representation of a smooth curve  $\mathbf{C}$  in  $\mathbf{E}^3$ . Define (a) the unit tangent T, (b) the principal unit normal N, (c) the curvature  $\kappa$ , (d) the unit binormal B, and (e) the torsion  $\tau$  for the curve C at each point. Then:
  - (f) Write the Frenet equations for the curve C.
  - (g) Describe the class of smooth space curves whose curvature is zero at each point.
  - (h) Describe the class of smooth space curves whose torsion is zero at each point.
- (i) Describe the class of smooth space curves whose curvature and torsion are positive and constant at each point.
- (j) Describe the class of smooth space curves whose curvature is positive and constant and whose torsion is zero at each point.
- 6. Consider the cylindrical coordinate system  $(r, \theta, z)$  in  $\mathbf{E}^3$  defined by  $x = r\cos(\theta)$ ,  $y = r\sin(\theta)$ , and z = z.
- (a) Compute the cellar (covariant) base vectors  $\{\mathbf{g}_1, \mathbf{g}_2, \mathbf{g}_3\} = \{\mathbf{g}_r, \mathbf{g}_\theta, \mathbf{g}_z\}$  in cylindrical coordinates.
- (b) Compute the reciprocal base vectors  $\{\mathbf{g}^1, \mathbf{g}^2, \mathbf{g}^3\} = \{\mathbf{g}^r, \mathbf{g}^\theta, \mathbf{g}^z\}$  in cylindrical coordinates.

- (c) Compute the roof (contravariant) components of the vector  $\mathbf{v} \sim (x^2 + y^2, z, -2)$  in cylindrical coordinates.
- 7. Let  $u^1, u^2, u^3$  be a (general) coordinate system in  $\mathbf{E}^3$ . For this coordinate system, define:
  - (a) the cellar (covariant) base vectors,
  - (b) the reciprocal base vectors, and
  - (c) the Christoffel symbols (of the second kind).
  - (d) Given that the Christoffel symbols obey

$$\tilde{\Gamma}^{i}_{jk} = \frac{\partial \tilde{u}^{i}}{\partial u^{p}} \left( \frac{\partial u^{q}}{\partial \tilde{u}^{j}} \frac{\partial u^{r}}{\partial \tilde{u}^{k}} \Gamma^{p}_{qr} + \frac{\partial^{2} u^{p}}{\partial \tilde{u}^{j}} \partial \tilde{u}^{k} \right)$$

under a coordinate transformation

$$u^{j} = f^{j}(u^{1}, u^{2}, u^{3}) \quad (j = 1, 2, 3),$$

do they transform like the components of a tensor? Why or why not?

- (e) Write Newton's second law  $\mathbf{f} = m\mathbf{a}$  for the motion of a point-mass in the  $u^1, u^2, u^3$  coordinate system.
- (f) Do the contravariant components of acceleration for a moving point-mass in  $E^3$  transform like the contravariant components of a first order tensor? Why or why not?