

Sec. 4.3: The Method of Undetermined Coefficients

HW p. 237: #2, 11, 15

Due: Wed., Oct. 13

Schaum's: pp. 94-102 (esp. 11.7)

Sec. 4.4: Variation of Parameters Due: Fri, Oct. 15

HW p. 242: #1 (on the interval $-\pi/2 < t < \pi/2$), 9, 13

Schaum's: pp. 103-109.

In these two sections we will address the problem of solving the n^{th} order linear nonhomogeneous equation

$$y^{(n)} + p_1(t)y^{(n-1)} + \dots + p_{n-1}(t)y' + p_n(t)y = g(t).$$

We will concentrate mainly on the case when the coefficients are constant.

Ex 1 (#2, p. 237) Find the general solution of

$$y^{(4)} - y = 3t + \cos(t).$$

Solution:

Step ①: $y = e^{rt}$ in $y^{(4)} - y = 0$ leads to $r^4 - 1 = 0$. Factoring yields $(r^2 - 1)(r^2 + 1) = 0$ or $(r-1)(r+1)(r^2 + 1) = 0$. Therefore the characteristic equation has roots: $r = 1, -1, i, -i$. The general solution of the associated homogeneous equation is $y_c(t) = c_1 e^t + c_2 e^{-t} + c_3 \cos(t) + c_4 \sin(t)$.

Step ②: We will use the method of undetermined coefficients to find a particular solution of the nonhomogeneous equation. Since $g(t) = 3t + \cos(t)$, we would normally use a trial form $y_p(t) = At + B + C\cos(t) + D\sin(t)$. However $\cos(t)$ and $\sin(t)$ are already solutions to the associated homogeneous

equation, so we must multiply $C\cos(t) + D\sin(t)$ by t . (That is, $s=1$ in the table 3.5.1 on p. 181.) Therefore we use a trial form

$$y_p(t) = At + B + t(C\cos(t) + D\sin(t))$$

where A, B, C , and D are constants to be determined. Then

$$y_p' = A + C\cos(t) + D\sin(t) + t(-C\sin(t) + D\cos(t))$$

$$y_p'' = 2(-C\sin(t) + D\cos(t)) + t(-C\cos(t) - D\sin(t))$$

$$y_p''' = 3(-C\cos(t) - D\sin(t)) + t(C\sin(t) - D\cos(t))$$

$$y_p^{(4)} = 4(C\sin(t) - D\cos(t)) + \underbrace{t(C\cos(t) + D\sin(t))}_{y_p - (At+B)}$$

We want

$$y_p^{(4)} - y_p = 3t + \cos(t)$$

so substituting expressions for $y_p^{(4)}$ and y_p from above yields

$$-(At+B) + 4(C\sin(t) - D\cos(t)) = 3t + \cos(t)$$

or

$$-At - B + 4C\sin(t) - 4D\cos(t) = 3t + 0 \cdot 1 + 0 \cdot \sin(t) + 1 \cdot \cos(t).$$

Equating like coefficients gives $-A = 3$, $-B = 0$, $4C = 0$, and $-4D = 1$.

Therefore $y_p(t) = -3t - \frac{1}{4}tsin(t)$.

Step ③: Write the general solution $y = y_c + y_p$:

$$y(t) = c_1 e^t + c_2 e^{-t} + c_3 \cos(t) + c_4 \sin(t) - 3t - \frac{1}{4}tsin(t)$$

where c_1, c_2, c_3 , and c_4 are arbitrary constants.

Variation of Parameters: A particular solution of

$$(*) \quad y^{(n)} + p_1(t)y^{(n-1)} + \dots + p_{n-1}(t)y' + p_n(t)y = g(t)$$

is $y_p(t) = u_1(t)y_1(t) + u_2(t)y_2(t) + \dots + u_n(t)y_n(t)$

where y_1, y_2, \dots, y_n is a fundamental set of solutions of the associated homogeneous equation of (*) and

$$u_i(t) = \int \frac{g(t)W_i(t)}{W(t)} dt \quad (i=1, 2, \dots, n).$$

Here $W(t)$ denotes the Wronskian of y_1, y_2, \dots, y_n at t and $W_i(t)$ is the determinant obtained from $W(t)$ by replacing the column containing $y_i(t)$ and its derivatives by the column $\begin{bmatrix} 0 \\ \vdots \\ 0 \\ 1 \end{bmatrix}$.

Notes: ① If you want to use variation of parameters for y_p then you must remember to place the DE (*) in standard form. That is, the leading coefficient must be 1. (See #13 on p. 242.)

② The variation of parameters formula is derived in the text on pp. 239-240.

Ex 2 [$(\#4, p. 242)$] Find the general solution of

$$y''' + y' = \sec(t)$$

on the interval $-\frac{\pi}{2} < t < \frac{\pi}{2}$.

Solution:

Step①: $y = e^{rt}$ in $y''' + y' = 0$ leads to $r^3 + r = 0$ or $r(r^2 + 1) = 0$.

Therefore the roots of the characteristic equation are $r = 0, i, -i$. Then

$y_1(t) = 1, y_2(t) = \cos(t), y_3(t) = \sin(t)$ are solutions of $y''' + y' = 0$.

$$W(t) = \begin{vmatrix} 1 & \cos(t) & \sin(t) \\ 0 & -\sin(t) & \cos(t) \\ 0 & -\cos(t) & -\sin(t) \end{vmatrix} \stackrel{\text{Expand by cofactors along column 1.}}{=} 1 \cdot \begin{vmatrix} -\sin(t) & \cos(t) \\ -\cos(t) & -\sin(t) \end{vmatrix} - 0 \cdot \begin{vmatrix} \cos(t) & \sin(t) \\ -\cos(t) & -\sin(t) \end{vmatrix} + 0 \cdot \begin{vmatrix} \cos(t) & \sin(t) \\ -\sin(t) & \cos(t) \end{vmatrix} = 1$$

Therefore y_1, y_2, y_3 is a F.S.S. for $y''' + y' = 0$.

Step②: We use variation of parameters to find y_p because $g(t) = \sec(t)$ is not an exponential, polynomial, or sine/cosine function (or sums or products of such).

$$\begin{aligned} \text{Then } y_p(t) &= u_1(t)y_1(t) + u_2(t)y_2(t) + u_3(t)y_3(t) \\ &= u_1(t) + \cos(t)u_2(t) + \sin(t)u_3(t). \end{aligned}$$

Replace $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ by this column.

$$W_1(t) = \begin{vmatrix} 0 & \cos(t) & \sin(t) \\ 0 & -\sin(t) & \cos(t) \\ 1 & -\cos(t) & -\sin(t) \end{vmatrix} \stackrel{\text{Expand by cofactors along column 1.}}{=} 1 \cdot \begin{vmatrix} \cos(t) & \sin(t) \\ -\sin(t) & \cos(t) \end{vmatrix} = 1$$

$$\therefore u_1(t) = \int \frac{g W_1}{W} dt = \int \frac{\sec(t) \cdot 1}{1} dt = \ln |\sec(t) + \tan(t)| + C$$

$$\text{Replace } \begin{bmatrix} \cos(t) \\ -\sin(t) \\ -\cos(t) \end{bmatrix} \text{ by this column.}$$

$$W_2(t) = \begin{vmatrix} 1 & 0 & \sin(t) \\ 0 & 0 & \cos(t) \\ 0 & 1 & -\sin(t) \end{vmatrix} \stackrel{\text{Expand by cofactors along column 1.}}{=} 1 \cdot \begin{vmatrix} 0 & \cos(t) \\ 1 & -\sin(t) \end{vmatrix} = -\cos(t)$$

$$\therefore u_2(t) = \int \frac{g W_2}{W} dt = \int \frac{\sec(t)(-\cos(t))}{1} dt = \int -1 dt = -t + C$$

$$\text{Replace } \begin{bmatrix} \sin(t) \\ \cos(t) \\ -\sin(t) \end{bmatrix} \text{ by this column.}$$

$$W_3(t) = \begin{vmatrix} 1 & \cos(t) & 0 \\ 0 & -\sin(t) & 0 \\ 0 & -\cos(t) & 1 \end{vmatrix} \stackrel{\text{Expand by cofactors along column 1.}}{=} 1 \cdot \begin{vmatrix} -\sin(t) & 0 \\ -\cos(t) & 1 \end{vmatrix} = -\sin(t)$$

$$\therefore u_3(t) = \int \frac{gW_3}{W} dt = \int \frac{\sec(t)(\sin(t))}{1} dt = \int \frac{-\sin(t)dt}{\cos(t)}$$

Let $v = \cos(t)$
Then $dv = -\sin(t)dt$

$$= \int \frac{dv}{v} = \ln|v| + C^0 = \ln|\cos(t)|$$

Consequently, $y_p = u_1 y_1 + u_2 y_2 + u_3 y_3$

$$= \ln|\sec(t) + \tan(t)| - t\cos(t) + \sin(t)\ln|\cos(t)|.$$

Step③: Write the general solution $y = y_c + y_p$:

$$y(t) = c_1 + c_2 \cos(t) + c_3 \sin(t) + \ln|\sec(t) + \tan(t)| - t\cos(t) + \sin(t)\ln|\cos(t)|$$

where c_1, c_2, c_3 are arbitrary constants.