# Recessive Solutions for Half-Linear DYNAMIC EQUATIONS 

Elvan Akin-Bohner*<br>University of Missouri-Rolla, 310 Rolla Building, MO 65409-0020<br>ZUZANA DošLÁ ${ }^{\dagger}$<br>Masaryk University Brno CZ-61137 Brno, Czech Republic


#### Abstract

We study recessive solutions of nonoscillatory half-linear dynamic equations. Recessive solutions are characterized using limit and integral properties.


AMS Subject Classification: 39A10.
Keywords: measure chains, time scales, half-linear dynamic equations, recessive solutions, nonoscillation.

## 1 Introduction

In this paper, we consider the half-linear dynamic equation

$$
\begin{equation*}
\left[a(t) \Phi\left(x^{\Delta}(t)\right)\right]^{\Delta}+b(t) \Phi\left(x^{\sigma}(t)\right)=0, \quad t \geq t_{0}, t_{0} \in \mathbb{T} \tag{1.1}
\end{equation*}
$$

where $\mathbb{T}$ is a time scale, a closed subset of real numbers. We assume that $\sup \mathbb{T}=\infty$, $\Phi(u)=|u|^{p-2} u, p>1$, and $\frac{1}{a}, b$ are positive right-dense continuous functions on $\mathbb{T}$.

Throughout this paper, by a solution of (1.1) we mean a nontrivial solution of (1.1).
The recessive solution for the linear dynamic equation

$$
\left[a(t) x^{\Delta}(t)\right]^{\Delta}+b(t) x^{\sigma}(t)=0
$$

has been characterized by the similar way as in the continuous case (i.e. $\mathbb{T}=\mathbb{R}$ ) and the discrete case (i.e. $\mathbb{T}=\mathbb{N}$ ), see [4, Theorem 4.61].

The extension of the notion of a recessive solution to the half-linear differential equation and difference equation is in general difficult problem and only partial results have been obtained, see e.g. [6, 7, 9, 10, 11] and [8, 12], respectively. We refer [15] for the discussion why $\frac{1}{a}$ has to be a right-dense continuous function on $\mathbb{T}$.

[^0]In this paper we study recessive solutions for (1.1) under the assumption

$$
\begin{equation*}
\int_{t_{0}}^{\infty} b(\tau) \Phi\left(\int_{\sigma(\tau)}^{\infty} \frac{\Delta s}{\Phi^{*}(a(s))}\right) \Delta \tau<\infty, \quad t_{0} \in \mathbb{T} \tag{1.2}
\end{equation*}
$$

where $\Phi^{*}$ is the inverse function of $\Phi$.
In the next section, we give a brief introduction to a time scale. In the third section, we obtain some essential results on solutions of half-linear dynamic equations and the Gronwall inequality on time scales. In the last two sections, we consider recessive solutions of halflinear dynamic equations.

## 2 Time Scale Calculus

In this section, we only mention preliminary results on time scales. More details of dynamic equations with applications can be found in $[4,5]$.

The forward jump operator $\sigma(t):=\inf \{s>t: s \in \mathbb{T}\} \in \mathbb{T}$, for all $t \in \mathbb{T}$ gives us the next point in $\mathbb{T}$ while the backward jump operator $\rho(t):=\sup \{s<t: s \in \mathbb{T}\} \in \mathbb{T}$ for all $t \in \mathbb{T}$ gives us the previous point in $\mathbb{T}$. The graininess function $\mu: \mathbb{T} \mapsto[0, \infty)$ is the distance between two consecutive points in $\mathbb{T}$, i.e., $\mu(t):=\sigma(t)-t$.

We define $\mathbb{T}^{\kappa}=\mathbb{T}-\{m\}$ if $m$ is a left-scattered maximum, otherwise $\mathbb{T}^{\kappa}=\mathbb{T}$. We assume $f, g: \mathbb{T} \mapsto \mathbb{R}$ and let $t \in \mathbb{T}^{\kappa}$. Delta derivative $f^{\Delta}(t)$ of $f(t)$ at $t$ is defined to be the number (provided it exists) if for given any $\varepsilon>0$, there is a neighborhood $U$ of $t$ such that

$$
\left|[f(\sigma(t))-f(s)]-f^{\Delta}(t)[\sigma(t)-s]\right| \leq \varepsilon|\sigma(t)-s|
$$

for all $s \in U$. The delta derivative $f^{\Delta}$ is the usual derivative if $\mathbb{T}=\mathbb{R}$ and the usual forward difference operator if $\mathbb{T}=\mathbb{Z}$.

For right-scattered points $(\sigma(t)>t)$ in $\mathbb{T}$, we have $f^{\Delta}(t)=\frac{f(\sigma(t))-f(t)}{\mu(t)}$ while $f^{\Delta}(t)=$ $\lim _{s \rightarrow t} \frac{f(t)-f(s)}{t-s}$ for right-dense points $(\sigma(t)=t)$ in $\mathbb{T}$ if the limit exists. For any $t \in \mathbb{T}$, we have $f^{\sigma}(t)=f(t)+\mu(t) f^{\Delta}(t)$, where $f^{\sigma}=f \circ \sigma$. The product and quotient rules are given by

$$
(f g)^{\Delta}=f^{\Delta} g+f^{\sigma} g^{\Delta}=f^{\Delta} g^{\sigma}+f g^{\Delta}, \quad\left(\frac{f}{g}\right)^{\Delta}=\frac{f^{\Delta} g-f g^{\Delta}}{g g^{\sigma}}
$$

if $g g^{\sigma} \neq 0$.
If $f: \mathbb{T} \mapsto \mathbb{R}$ is continuous at each right-dense point $t \in \mathbb{T}$ and its left sided limits exist as a finite number at all left-dense points $(\rho(t)=t)$ on $\mathbb{T}$, then it is called a rightdense continuous (rd-continuous) function. For $a, b \in \mathbb{T}$ and a differentiable function $f$, the Cauchy integral of $f^{\Delta}$ is defined by

$$
\int_{a}^{b} f^{\Delta}(s) \Delta s=f(b)-f(a)
$$

The exponential function $e_{p}\left(t, t_{0}\right)$ on $\mathbb{T}$ is for each fixed $t_{0} \in \mathbb{T}$ the unique solution of the initial value problem

$$
x^{\Delta}=p(t) x, x\left(t_{0}\right)=1
$$

where $p: \mathbb{T} \mapsto \mathbb{R}$ is regressive $\left(1+\mu(t) p(t) \neq 0\right.$ for all $\left.t \in \mathbb{T}^{\mathbb{K}}\right)$ and rd-continuous. Following properties of exponential functions in time scales are important to prove Gronwall's inequality, see [2] and [3], respectively. All the other properties of exponential functions in time scales can be found in [4].

Theorem 2.1. Let $p: \mathbb{T} \mapsto \mathbb{R}$ be positively regressive, i.e., $1+\mu(t) p(t)>0$ for all $\in \mathbb{T}^{\mathrm{K}}$ and rd-continuous. Then we have

1. $e_{p}\left(t, t_{0}\right)>0$ for all $t \in \mathbb{T}$,
2. $e_{p}(t, s) \leq e^{\int_{s}^{t} p(\tau) \Delta \tau}$.

The time scale version of L'Hopital's Rule can be found in [1] and is useful to classify nonoscillatory solutions of equation (1.1).

Theorem 2.2. Assume $f$ and $g$ are differentiable functions on $\mathbb{T}$ with

$$
\lim _{t \rightarrow t_{0}^{-}} f(t)=\lim _{t \rightarrow t_{0}^{-}} g(t)=0 \quad \text { for some left-dense } t_{0} \in \overline{\mathbb{T}}, \quad \bar{T}=\mathbb{T} \cup \sup \mathbb{T} \cup \inf \mathbb{T}
$$

Suppose there exists $\varepsilon>0$ with

$$
g(t)>0, \quad g^{\Delta}(t)<0 \quad \text { for all } t \in L_{\mathcal{\varepsilon}}\left(t_{0}\right), \quad L_{\mathcal{\varepsilon}}\left(t_{0}\right)=\left\{t \in \mathbb{T}: 0<t_{0}-t<\varepsilon\right\} .
$$

Then we have

$$
\liminf _{t \rightarrow t_{0}^{-}} \frac{f^{\Delta}(t)}{g^{\Delta}(t)} \leq \liminf _{t \rightarrow t_{0}^{-}} \frac{f(t)}{g(t)} \leq \operatorname{limsusu}_{t \rightarrow t_{0}^{-}} \frac{f(t)}{g(t)} \leq \limsup _{t \rightarrow t_{0}^{-}} \frac{f^{\Delta}(t)}{g^{\Delta}(t)}
$$

The chain rule on time scales by Pötzsche ([16]) plays an important role for integral characterization of recessive solutions.

Theorem 2.3. Let $f: \mathbb{R} \mapsto \mathbb{R}$ be continuously differentiable and suppose $g: \mathbb{T} \mapsto \mathbb{R}$ is delta differentiable. Then $f \circ g: \mathbb{T} \mapsto \mathbb{R}$ is delta differentiable and the formula

$$
(f \circ g)^{\Delta}(t)=g^{\Delta}(t) \int_{0}^{1} f^{\prime}\left(g(t)+h \mu(t) g^{\Delta}(t)\right) d h
$$

holds.

## 3 Nonoscillatory solutions

The half-linear equation (1.1) has the homogeneity property, i.e., if $x$ is a solution of (1.1), then $\lambda x$ is also a solution of (1.1), where $\lambda \in \mathbb{R}$. If $x$ is a solution of (1.1), then

$$
x^{[1]}(t)=a(t) \Phi\left(x^{\Delta}(t)\right), \quad t \in \mathbb{T}
$$

is called the quasi-derivative of $x$.
A solution $x$ of (1.1) is said to be nonoscillatory if there exists $T \geq t_{0}, T \in \mathbb{T}$ such that $x(t) x^{\sigma}(t)>0$ for $t \geq T$. Equation (1.1) is called nonoscillatory if it has a nonoscillatory
solution. Due to the Sturm-theory ([14]), if (1.1) has a nonoscillatory solution, then all its solutions are nonoscillatory.

The condition (1.2) implies

$$
\begin{equation*}
\int_{t_{0}}^{\infty} \frac{\Delta \tau}{\Phi^{*}(a(\tau))}<\infty, \quad t_{0} \in \mathbb{T} \tag{3.1}
\end{equation*}
$$

Denote

$$
\begin{equation*}
A(t)=\int_{t}^{\infty} \frac{\Delta \tau}{\Phi^{*}(a(\tau))} \tag{3.2}
\end{equation*}
$$

We start with the properties of nonoscillatory solutions of (1.1).
Lemma 3.1. Assume that (3.1) holds. If $x$ is a nonoscillatory solution of (1.1), then

1. $x$ and $x^{[1]}$ are eventually strongly monotone;

## 2. $x$ is bounded;

3. if $\lim _{t \rightarrow \infty} x(t)=0$, then $\lim _{t \rightarrow \infty} x^{[1]}(t)=c$, where $-\infty \leq c<0$ or $0<c \leq \infty$ according to whether $x(t)>0$ or $x(t)<0$ for large $t \in \mathbb{T}$, respectively.

Proof. Without loss of generality, we assume that $x(t)>0$ for $t \geq t_{0}, t_{0} \in \mathbb{T}$.
From (1.1), $\left(x^{[1]}\right)^{\Delta}(t)<0$ for large $t \in \mathbb{T}$, thus $x^{[1]}$ is eventually decreasing and $x^{\Delta}$ is eventually positive or negative, i.e., $x$ is eventually strongly monotone.

Since $x^{[1]}$ is eventually decreasing, $x^{[1]}(t) \leq x^{[1]}\left(t_{0}\right)$ for $t \geq t_{0}$. This implies that

$$
x(t) \leq x\left(t_{0}\right)+\Phi^{*}\left(x^{[1]}\left(t_{0}\right)\right) \int_{t_{0}}^{t} \frac{\Delta \tau}{\Phi^{*}(a(\tau))}
$$

Since (3.1) holds, $x$ is bounded. This completes the proof of the second part.
Finally, since $x$ is eventually strongly monotone, positive and $\lim _{t \rightarrow \infty} x(t)=0, x$ is eventually decreasing and so $x^{\Delta}(t)<0$ for large $t \in \mathbb{T}$. This implies that $x^{[1]}(t)<0$ for large $t \in \mathbb{T}$. If $\lim _{t \rightarrow \infty} x^{[1]}(t)=0$, then integrating (1.1) yields that $x^{[1]}(t)>0$ for large $t$, which gives a contradiction.

From Lemma 3.1 and Theorem 2.2 it follows that if (3.1) holds, then any nonoscillatory solution of (1.1) is bounded and is one the following types:

$$
\begin{aligned}
& \text { Type (a) : } \lim _{t \rightarrow \infty} \frac{x(t)}{A(t)}=c \quad 0<|c|<\infty, \\
& \text { Type (b) : } \lim _{t \rightarrow \infty} \frac{x(t)}{A(t)}=\infty .
\end{aligned}
$$

The following Gronwall Inequality plays an important role to obtain the uniqueness result on solutions of Type (a). It is an extension of [13, Lemma 4.1] for the continuous case and [8, Lemma 2.3] for the discrete case.

Lemma 3.2. Let $z, w$ be two nonnegative $r d$-continuous functions on $\mathbb{T}$ such that

$$
\int_{T}^{\infty} w(\tau) z^{\sigma}(\tau) \Delta \tau<\infty
$$

and

$$
\int_{T}^{\infty} w(\tau) \Delta \tau<\infty
$$

for $T \in \mathbb{T}$. If $z(t) \leq \int_{t}^{\infty} w(\tau) z^{\sigma}(\tau) \Delta \tau, t \geq T$, then $z(t)=0$ for all $t \geq T$.
Proof. Define $v(t):=\int_{t}^{\infty} w(\tau) z^{\sigma}(\tau) \Delta \tau$. This implies that $(0 \leq) z(t) \leq v(t), t \geq T$.
From here and the fact $v^{\Delta}(t)=-w(t) z^{\sigma}(t)$, we obtain

$$
v^{\Delta}(t)+w(t) v^{\sigma}(t) \geq 0 .
$$

Since $w(t) \geq 0$ and $\int_{T}^{\infty} w(\tau) \Delta \tau<\infty, e_{w}(t, T)$ is bounded and positive by Theorem 2.1. By the product rule on $\mathbb{T}$,

$$
\left(e_{w}(t, T) v(t)\right)^{\Delta}=\left(v^{\Delta}(t)+w(t) v^{\sigma}(t)\right) e_{w}(t, T) \geq 0 .
$$

Since $\lim _{t \rightarrow \infty} v(t)=0$ and $e_{w}(t, T)$ is bounded, $e_{w}(t, T) v(t) \leq 0$ for $t \geq T$ and so $v(t)=0$ for $t \geq T$. This implies that $z(t)=0$ for $t \geq T$.

Now, we can prove the existence of a unique (up to a multiplicity constant) vanishing solution.

Theorem 3.3. Assume (1.2). For any $c \neq 0$ equation (1.1) has a unique (nonoscillatory) solution u of Type (a), i. e.,

$$
\begin{equation*}
\lim _{t \rightarrow \infty} u(t)=0, \quad \lim _{t \rightarrow \infty} u^{[1]}(t)=c, \quad c \in \mathbb{R}-\{0\} . \tag{3.3}
\end{equation*}
$$

Proof. The existence. We choose $t_{1} \geq t_{0}, t_{1} \in \mathbb{T}$ such that

$$
\int_{t_{1}}^{\infty} b(t) \Phi\left(\int_{\sigma(t)}^{\infty} \frac{\Delta \tau}{\Phi^{*}(a(\tau))}\right) \Delta t<1-\frac{1}{\Phi(2)}
$$

and denote $X$ as a Banach space of all bounded and continuous functions defined for every $t \geq t_{1}$ with the supremum norm. Define the set $\Omega \subset X$ by

$$
\Omega=\left\{u \in X: \frac{1}{2} A(t) \leq u(t) \leq A(t), t \geq t_{1}\right\} .
$$

Obviously, $\Omega$ is bounded, closed and convex. We now consider the operator $K: \Omega \mapsto X$ defined by

$$
K u(t)=\int_{t}^{\infty} \frac{1}{\Phi^{*}(a(s))} \Phi^{*}\left(1-\int_{s}^{\infty} b(\tau) \Phi\left(u^{\sigma}(\tau)\right) \Delta \tau\right) \Delta s .
$$

Then

$$
\frac{1}{2} A(t) \leq K u(t) \leq A(t)
$$

so that $K(\Omega) \subset \Omega$. Obviously, $K(\Omega)$ is relatively compact in $X$, and $K$ is continuous in $X$. By Schauder fixed point theorem, there exists $u$ in $\Omega$ such that $K u=u$. Therefore, (3.3) holds.

The uniqueness. Without loss of generality, assume $x$ and $z$ are two positive solutions of (1.1) for $t \geq T, T \in \mathbb{T}$ such that

$$
\begin{gathered}
\lim _{t \rightarrow \infty} x(t)=\lim _{t \rightarrow \infty} z(t)=0, \\
\lim _{t \rightarrow \infty} x^{[1]}(t)=\lim _{t \rightarrow \infty} z^{[1]}(t)=c<0 .
\end{gathered}
$$

Since $x^{[1]}$ and $z^{[1]}$ are eventually decreasing, we can assume that

$$
\begin{equation*}
0<-\frac{c}{2}<-x^{[1]}<-c, \quad 0<-\frac{c}{2}<-z^{[1]}<-c . \tag{3.4}
\end{equation*}
$$

We have

$$
\begin{equation*}
\int_{t}^{\infty} \frac{1}{\Phi^{*}(a(\tau))} \Phi^{*}\left(-x^{[1]}(\tau)\right) \Delta \tau=x(t) \tag{3.5}
\end{equation*}
$$

and

$$
\begin{equation*}
\int_{t}^{\infty} \frac{1}{\Phi^{*}(a(\tau))} \Phi^{*}\left(-z^{[1]}(\tau)\right) \Delta \tau=z(t) \tag{3.6}
\end{equation*}
$$

from the quasi-derivative of $x$ and $z$, respectively. From (3.4), we have

$$
\begin{equation*}
-\Phi^{*}\left(\frac{c}{2}\right) A(t)<x(t)<-\Phi^{*}(c) A(t) \tag{3.7}
\end{equation*}
$$

and

$$
\begin{equation*}
-\Phi^{*}\left(\frac{c}{2}\right) A(t)<z(t)<-\Phi^{*}(c) A(t) \tag{3.8}
\end{equation*}
$$

Since $\Phi(r)=r^{p-1}$ for $r>0$, by the mean value theorem we obtain

$$
|\Phi(x(t))-\Phi(z(t))| \leq(p-1)(w(t))^{p-2}|x(t)-z(t)|
$$

where $w(t)=\max \{x(t), z(t)\}$ if $p>2, w(t)=\min \{x(t), z(t)\}$ if $1<p<2$, and $w(t)=1$ if $p=2$. Then for any $p>1$, there exists a positive constant $L$ such that

$$
(p-1)(w(t))^{p-2} \leq L(A(t))^{p-2}
$$

by (3.7) and (3.8). By (3.5) and (3.6), we have

$$
|\Phi(x(t))-\Phi(z(t))| \leq L(A(t))^{p-2}|x(t)-z(t)|
$$

and so

$$
\begin{equation*}
|\Phi(x(t))-\Phi(z(t))| \leq L(A(t))^{p-2} \int_{t}^{\infty} \frac{1}{\Phi^{*}(a(\tau))}\left|\Phi^{*}\left(-x^{[1]}\right)(\tau)-\Phi^{*}\left(-z^{[1]}\right)(\tau)\right| \Delta \tau . \tag{3.9}
\end{equation*}
$$

Similarly, since

$$
\lim _{t \rightarrow \infty} \Phi^{*}\left(x^{[1]}\right)(t)=\lim _{t \rightarrow \infty} \Phi^{*}\left(z^{[1]}\right)(t)=\Phi^{*}(c)<0
$$

there exists a positive constant $H$ such that

$$
\begin{equation*}
\left|\Phi^{*}\left(x^{[1]}(t)\right)-\Phi^{*}\left(z^{[1]}(t)\right)\right| \leq H\left|x^{[1]}(t)-z^{[1]}(t)\right| . \tag{3.10}
\end{equation*}
$$

Integrating (1.1) from $t$ to $\infty$, we have

$$
x^{[1]}(t)=c+\int_{t}^{\infty} b(\tau) \Phi\left(x^{\sigma}(t)\right) \Delta \tau
$$

and

$$
z^{[1]}(t)=c+\int_{t}^{\infty} b(\tau) \Phi\left(z^{\sigma}(t)\right) \Delta \tau
$$

From (3.9) and (3.10), we have

$$
\begin{aligned}
& \left|\Phi^{*}\left(x^{[1]}(t)\right)-\Phi^{*}\left(z^{[1]}(t)\right)\right| \leq H \int_{t}^{\infty} b(\tau)\left|\Phi\left(x^{\sigma}(\tau)\right)-\Phi\left(z^{\sigma}(\tau)\right)\right| \Delta \tau \\
& \left.\quad \leq H L \int_{t}^{\infty} b(\tau)\right)\left(A^{\sigma}(\tau)\right)^{p-2} \int_{\sigma(\tau)}^{\infty} \frac{1}{\Phi^{*}(a(s))}\left|\Phi^{*}\left(-x^{[1]}(s)\right)-\Phi^{*}\left(-z^{[1]}(s)\right)\right| \Delta s \Delta \tau .
\end{aligned}
$$

Put $u(t)=\sup _{t \geq T}\left|\Phi^{*}\left(x^{[1]}(t)\right)-\Phi^{*}\left(z^{[1]}(t)\right)\right|$. Then

$$
\begin{aligned}
u(t) & \leq H L \int_{t}^{\infty} b(\tau)\left(A^{\sigma}(\tau)\right)^{p-2} \int_{\sigma(\tau)}^{\infty} \frac{1}{\Phi^{*}(a(s))} u(s) \Delta s \Delta \tau \\
& \leq H L \int_{t}^{\infty} b(\tau)\left(A^{\sigma}(\tau)\right)^{p-2} u^{\sigma}(\tau) \int_{\sigma(\tau)}^{\infty} \frac{1}{\Phi^{*}(a(s))} \Delta s \Delta \tau \\
& =H L \int_{t}^{\infty} b(\tau) \Phi\left(A^{\sigma}(\tau)\right) u^{\sigma}(\tau) \Delta \tau .
\end{aligned}
$$

By (1.2), and Lemma 3.2, $u(t)=0$ for $t \geq T$. This implies that $x^{[1]}(t)=z^{[1]}(t)$ for all $t \geq T$, and this completes the proof.

Corollary 3.4. Assume (1.2) and $u$ is a solution of Type (a). Then any solution $x$ of (1.1) linearly independent of $u$ is of Type (b).

Proof. We will prove that if $u$ and $w$ are two solutions of Type (a), then $u, w$ are linearly dependent, i.e., there exists $\lambda \in \mathbb{R}-\{0\}$ such that $u=\lambda w$.

Let

$$
\begin{gathered}
\lim _{t \rightarrow \infty} u(t)=\lim _{t \rightarrow \infty} w(t)=0 \\
\lim _{t \rightarrow \infty} u^{[1]}(t)=c \text { and } \lim _{t \rightarrow \infty} w^{[1]}(t)=d,
\end{gathered}
$$

where $c, d \in \mathbb{R}-\{0\}$, and let $z$ be the solution of (1.1) such that

$$
z=\Phi^{*}\left(\frac{c}{d}\right) w .
$$

Then $\lim _{t \rightarrow \infty} z(t)=0$ and because

$$
z^{[1]}=\frac{c}{d} w^{[1]},
$$

we have

$$
\lim _{t \rightarrow \infty} z^{[1]}(t)=\frac{c}{d} \lim _{t \rightarrow \infty} w^{[1]}(t)=c .
$$

By Theorem 3.3, $z=u$. Consequently, any solution $x$ linearly independent of $u$ must be of Type (b).

If $\mathbb{T}=\mathbb{N}$, then Theorem 3.3 gives $[8$, Theorem 3.4] and if $\mathbb{T}=\mathbb{R}$, then it gives [9, Theorem A and Theorem B].

## 4 Recessive Solutions

Our main result is the following characterization of solutions of Type (a). The continuous case of the part of the following theorem can be found in [9, Theorem 1].

Theorem 4.1. Assume (1.2). The following statements are equivalent:
(a) Solution $u$ is of Type (a).
(b) Solution u satisfies the limit property, i.e.,

$$
\begin{equation*}
\lim _{t \rightarrow \infty} \frac{u(t)}{x(t)}=0 \tag{4.1}
\end{equation*}
$$

for any solution $x$ linearly independent of $u$.
(c) Solution u satisfies the Riccati property, i.e.,

$$
\begin{equation*}
\frac{u^{\Delta}(t)}{u(t)}<\frac{x^{\Delta}(t)}{x(t)} \quad \text { for large } t \in \mathbb{T} \tag{4.2}
\end{equation*}
$$

for any solution $x$ linearly independent of $u$.
Proof. Without loss of generality, assume $u$ and $x$ are eventually positive solutions.
"(a) $\Longrightarrow$ (b)": If $x$ is a solution of (1.1) such that $x \neq \lambda u, \lambda \in \mathbb{R}-\{0\}$, then by Corollary $3.4 x$ is of Type (b). Consequently, (4.1) holds.
"(b) $\Longrightarrow$ (c)": From (4.1) we have that the function $\frac{u}{x}$ is eventually positive and eventually decreasing. Thus

$$
\left(\frac{u}{x}\right)^{\Delta}(t)=\frac{u^{\Delta}(t) x(t)-x^{\Delta}(t) u(t)}{x(t) x^{\sigma}(t)}<0 \text { for large } t \in \mathbb{T},
$$

from where (4.2) follows.
"(c) $\Longrightarrow(\mathrm{a})$ ": Let there exist a solution $u$ satisfying (4.2) for any $x$ linearly independent of $u$. Assume that $u$ is of Type (b), i.e.

$$
\begin{equation*}
\lim _{t \rightarrow \infty} \frac{u(t)}{A(t)}=\infty . \tag{4.3}
\end{equation*}
$$

By Theorem 3.3, there exists a unique solution $z$ such that $\lim _{t \rightarrow \infty} \frac{z(t)}{A(t)}=1$. Obviously, $z$ is linearly independent of $u$ and we have

$$
\frac{u^{\Delta}(t)}{u(t)}<\frac{z^{\Delta}(t)}{z(t)} \quad \text { for large } t \in \mathbb{T}
$$

This implies that

$$
\left(\frac{u}{z}\right)^{\Delta}(t)=\frac{u^{\Delta}(t) z(t)-z^{\Delta}(t) u(t)}{z(t) z^{\sigma}(t)}<0 \text { for large } t \in \mathbb{T}
$$

and so $\frac{u}{z}$ is eventually decreasing and eventually positive. Therefore,

$$
\lim _{t \rightarrow \infty} \frac{u(t)}{z(t)}=c, \quad 0 \leq c<\infty
$$

which gives a contradiction with (4.3).
By Theorems 3.3 and 4.1, equation (1.1) possesses a unique (up to a nonzero multiplicative factor) solution $u$ with the property (4.2). In accordance with the discrete case, such a solution is called a recessive solution of (1.1) and every solution of (1.1), which is not a recessive solution is called a dominant solution of (1.1).

Remark 4.2. The property (4.2) is closely related with the minimal solution of the generalized Riccati dynamic equation ([14])

$$
\begin{equation*}
R[w]:=w^{\Delta}+b(t)+S[w, a](t)=0, \tag{4.4}
\end{equation*}
$$

where

$$
S[w, a](t)=\left\{\begin{array}{cc}
\frac{p-1}{\Phi^{*}(a(t))}|w(t)|^{\beta} & \text { at right-dense } t \\
\frac{w(t)}{\mu(t)}\left(1-\frac{\text { at right-scattered } t .}{\Phi\left(\Phi^{*}(a(t))+\mu(t) \Phi^{*}(w(t))\right)}\right)
\end{array}\right.
$$

Indeed, if $x$ is a solution of (1.1) with $\left(a x x^{\sigma}\right)(t)>0$ for $t \geq t_{0}, t_{0} \in \mathbb{T}$, then

$$
w(t)=\frac{x^{[1]}(t)}{\Phi(x(t))}
$$

is a solution of (4.4) satisfying

$$
\left(\Phi^{*}(a)+\mu \Phi^{*}(w)\right)(t)>0 \quad \text { for } t \geq t_{0}
$$

see [14]. Thus, the property (4.2), or equivalently

$$
\frac{u^{[1]}(t)}{\Phi(u(t))}<\frac{x^{[1]}(t)}{\Phi(x(t))} \quad \text { for large } t \in \mathbb{T},
$$

means that the solution $w_{u}$ of (4.4) corresponding to the recessive solution $u$ of (1.1) is smaller than any other solution of (4.4) for large $t$.

It is an open problem whether the minimal solution of (4.4) and recessive solution of (1.1) exist without assuming $b(t)>0$ and (1.2).

## 5 Integral characterization of recessive solutions

The integral and summation characterization of recessive solutions for differential and difference equations has been investigated in $[6,10,11]$ and $[8,12]$, respectively. In this section, we extend some of these results to the dynamic equations.

Lemma 5.1. Suppose (3.1) and $A$ is defined as in (3.2). Then

$$
\begin{equation*}
\int_{T}^{\infty} \frac{-A^{\Delta}(\tau)}{A^{m}(\tau) A(\sigma(\tau))} \Delta \tau=\infty, T \in \mathbb{T} \tag{5.1}
\end{equation*}
$$

if $0<m \leq 1$, and

$$
\begin{equation*}
\int_{T}^{\infty} \frac{-A^{\Delta}(\tau)}{A(\tau) A^{m}(\sigma(\tau))} \Delta \tau=\infty, T \in \mathbb{T} \tag{5.2}
\end{equation*}
$$

if $m \geq 1$.
Proof. By the quotient rule, we have

$$
\left(\frac{1}{A^{m}(t)}\right)^{\Delta}=\frac{-\left(A^{m}\right)^{\Delta}(t)}{A^{m}(t) A^{m}(\sigma(t))}
$$

By Theorem 2.3, we have

$$
\left(A^{m}\right)^{\Delta}(t)=\left(t^{m} \circ A\right)^{\Delta}=m A^{\Delta}(t) \int_{0}^{1}\left(A(t)+h \mu(t) A^{\Delta}(t)\right)^{m-1} d h .
$$

Obviously,

$$
0<A^{\sigma} \leq A+h \mu A^{\Delta} \leq A .
$$

If $0<m \leq 1$, then

$$
\left(A^{m}\right)^{\Delta}(t) \geq m A^{\Delta}(t) \int_{0}^{1} A^{m-1}(\sigma(t)) d h=m A^{\Delta}(t) A^{m-1}(\sigma(t))
$$

and so

$$
\left(\frac{1}{A^{m}(t)}\right)^{\Delta} \leq \frac{-m A^{\Delta}(t)}{A^{m}(t) A(\sigma(t))}
$$

Integrating above from $T$ to $t, T \in \mathbb{T}$ yields

$$
\frac{1}{A^{m}(t)}-\frac{1}{A^{m}(T)} \leq \int_{T}^{t} \frac{-m A^{\Delta}(\tau)}{A^{m}(\tau) A(\sigma(\tau))} \Delta \tau .
$$

Since $\lim _{t \rightarrow \infty} A(t)=0$, we obtain (5.1).
Similarly, if $m \geq 1$, then

$$
\left(A^{m}\right)^{\Delta}(t) \geq m A^{\Delta}(t) \int_{0}^{1} A^{m-1}(t) d h=m A^{\Delta}(t) A^{m-1}(t)
$$

which implies that

$$
\begin{equation*}
\left(\frac{1}{A^{m}(t)}\right)^{\Delta} \leq \frac{-m A^{\Delta}(t)}{A(t) A^{m}(\sigma(t))} \tag{5.3}
\end{equation*}
$$

and integrating above from $T$ to $t, T \in \mathbb{T}$ yields

$$
\frac{1}{A^{m}(t)}-\frac{1}{A^{m}(T)} \leq \int_{T}^{t} \frac{-m A^{\Delta}(\tau)}{A(\tau) A^{m}(\sigma(\tau))} \Delta \tau .
$$

Since $\lim _{t \rightarrow \infty} A(t)=0$, we obtain (5.2).
The following theorem is new for discrete case while the continuous version of it can be found in [11, Proposition 7].

Theorem 5.2. Assume (1.2) holds. If $u$ is a recessive solution of (1.1), then there exists $T \in \mathbb{T}, T \geq t_{0}$ such that

$$
\begin{align*}
& I:=\int_{T}^{\infty} \frac{\Delta \tau}{\Phi^{*}(a(\tau))\left(u(\tau) u^{\sigma}(\tau)\right)^{m}}=\infty \quad \text { for any } m \geq 1  \tag{5.4}\\
& J:=\int_{T}^{\infty} \frac{\Delta \tau}{\Phi^{*}(a(\tau)) u^{m}(\tau) u^{\sigma}(\tau)}=\infty \quad \text { for any } m \in(0,1] \tag{5.5}
\end{align*}
$$

and

$$
\begin{equation*}
S:=\int_{T}^{\infty} \frac{u^{\Delta}(\tau)}{u^{[1]}(\tau) u(\tau) u^{\sigma}(\tau)} \Delta \tau=\infty . \tag{5.6}
\end{equation*}
$$

Proof. Let $u$ be a recessive solution. By Theorem 4.1, $u$ is of Type (a). Without loss of generality, we assume $u$ is eventually positive satisfying

$$
\lim _{t \rightarrow \infty} u(t)=0, \quad \lim _{t \rightarrow \infty} u^{[1]}(t)=c<0
$$

By Theorem 2.2, there exists $T \in \mathbb{T}, T \geq t_{0}$ such that

$$
u(t)<-2 c A(t) \text { for } t \geq T
$$

So since $A$ is decreasing, and (5.3) holds, we have

$$
\begin{aligned}
\int_{T}^{t} \frac{\Delta \tau}{\Phi^{*}(a(\tau))\left(u(\tau) u^{\sigma}(\tau)\right)^{m}} & >\frac{1}{4^{m} c^{2 m}} \int_{T}^{t} \frac{-A^{\Delta}(\tau) \Delta \tau}{A^{m}(\tau) A^{m}(\sigma(\tau))} \\
& >\frac{1}{4^{m} c^{2 m} A^{m-1}(T)} \int_{T}^{t} \frac{-A^{\Delta}(\tau) \Delta \tau}{A(\tau) A^{m}(\sigma(\tau))}
\end{aligned}
$$

Passing $t \rightarrow \infty$ and applying Lemma 5.1 we get (5.4). By the same argument we get (5.5).
Similarly, integrals $S$ and

$$
\int_{T}^{\infty} \frac{-u^{\Delta}(\tau)}{u(\tau) u^{\sigma}(\tau)} \Delta \tau
$$

have the same character, i.e., they are either both convergent or both divergent. Since

$$
\int_{T}^{\infty}\left(\frac{1}{A(\tau)}\right)^{\Delta} \Delta \tau=\infty
$$

we have

$$
\int_{T}^{\infty} \frac{-u^{\Delta}(\tau)}{u(\tau) u^{\sigma}(\tau)} \Delta \tau=\int_{T}^{\infty}\left(\frac{1}{u(\tau)}\right)^{\Delta} \Delta \tau=\infty,
$$

and so (5.6) holds.

It is an open problem whether $I=\infty, J=\infty$ or $S=\infty$ implies that $u$ is a recessive solution. A partial answer gives the following theorem.

Corollary 5.3. Assume (3.1) and

$$
\begin{equation*}
\int_{t_{0}}^{\infty} b(\tau) \Delta \tau<\infty . \tag{5.7}
\end{equation*}
$$

Then the following statements are equivalent:
(a) $u$ is a recessive solution of (1.1).
(b) (5.4) holds.
(c) (5.5) holds.
(d) (5.6) holds.

Proof. First we prove that any solution is bounded together with its quasiderivative. By Lemma 3.1 (ii), any solution $x$ of (1.1) is bounded. Integrating (1.1) from $t$ to $\infty$ and using (5.7) the boundedness of $x^{[1]}$ follows. Hence, a solution is of Type (b) if and only if $\lim _{t \rightarrow \infty} u(t)=c, 0<|c|<\infty$.

Now by Theorem 5.2, it is enough to prove that if (5.4), (5.5) or (5.6) holds, then $u$ is a recessive solution of (1.1).

Assume $I=\infty$ or $J=\infty$. Then, in view of (3.1), we get $\lim _{t \rightarrow \infty} u(t)=0$. Since $u^{[1]}$ is bounded, $u$ is of Type (a) and by Theorem 4.1 solution $u$ is recessive.

Assume $S=\infty$. If $u$ is dominant, then $\lim _{t \rightarrow \infty} u(t)=c, 0<|c|<\infty$. Because $u^{[1]}$ is bounded and

$$
\int_{T}^{\infty} u^{\Delta}(\tau) \Delta \tau<\infty,
$$

we have $S<\infty$, a contradiction.
Lemma 5.4. Assume (1.2) and

$$
\begin{equation*}
\int_{t_{0}}^{\infty} b(\tau) \Delta \tau=\infty, t_{0} \in \mathbb{T} \tag{5.8}
\end{equation*}
$$

Then any solution $x$ of (1.1) satisfies $x(t) x^{[1]}(t)<0$ for $t \in \mathbb{T}$.
Proof. By Theorem 3.3, equation (1.1) is nonoscillatory. Without loss of generality, we assume that $x(t)>0$ for $t \geq t_{0}, t_{0} \in \mathbb{T}$. Then $x^{[1]}(t)$ is decreasing for $t \geq t_{0}$. Assume that $x^{[1]}(t)>0$ for $t \geq t_{1} \geq t_{0}, t_{1} \in \mathbb{T}$. This implies that $x(t)$ is increasing $t \geq t_{1}$. Integrating equation (1.1) from $t_{1}$ to $t$ yields

$$
x^{[1]}(t) \leq x^{[1]}\left(t_{1}\right)-\Phi\left(x\left(t_{0}\right)\right) \int_{t_{1}}^{t} b(s) \Delta s
$$

where we also use the monotonicity of $x$. But this contradicts with the positivity of $x^{[1]}$ as $t \rightarrow \infty$.

Moreover, the following result holds for the special choice of $\mathbb{T}=\mathbb{N}$.
Theorem 5.5. [12, Theorem 1] Let $\mathbb{T}=\mathbb{N}, p \in(1,2]$ and let $u(t) u^{\Delta}(t)<0$ for large $t$. If (5.6) holds, then $u$ is a recessive solution of (1.1).

By Theorem 5.2, Lemma 5.4, and Theorem 5.5 we improve the previous result.
Corollary 5.6. Let $\mathbb{T}=\mathbb{N}, p \in(1,2]$, (1.2) and (5.8) hold. Then $u$ is a recessive solution if and only if (5.6) holds.

## Concluding remarks.

(1) Does exist the minimal solution of the Riccati dynamical equation (4.4) without assuming (1.2)?
(2) Theorem 3.3 can be extended for $b$ which can change sign replacing (1.2) by

$$
\begin{equation*}
\int_{t_{0}}^{\infty}|b(\tau)| \Phi\left(\int_{\sigma(\tau)}^{\infty} \frac{\Delta s}{\Phi^{*}(a(s))}\right) \Delta \tau<\infty . \tag{5.9}
\end{equation*}
$$

The proof is a similar as that one in [7] where the continuous case is treated.
(3) Does it hold Corollary 5.6 for any time scales?
(4) Let $p>2$, (5.9) holds and

$$
\int_{t_{0}}^{\infty} \Phi^{*}\left(\frac{1}{a(s)} \int_{t_{0}}^{t}|b(s)| \Delta s\right) \Delta \tau=\infty, \quad t_{0} \in \mathbb{T} .
$$

We conjecture that in this case the integral characterization (5.6) can fail.
Acknowledgement. Second author is supported by the Research Project 0021622409 of the Ministery of Education of the Czech Republic and Grant 201/07/0145 of the Czech Grant Agency.

## References

[1] R. Agarwal and M. Bohner, Basic calculus on time scales and some of its applications. Results Math. 35(1-2)(1999):3-22.
[2] E. Akın-Bohner, M. Bohner and F. Akın, Pachpatte inequalities on time scales. Journal of Inequalities in Pure and Applied Mathematics 6(1) (2005), 1-23.
[3] M. Bohner, Some oscillation criteria for first order delay dynamic equations. Far East Journal of Applied Mathematics 18(3)(2005), 289-304.
[4] M. Bohner and A. Peterson, Dynamic Equations on Time Scales: An Introduction with Applications. Birkhäuser, Boston 2001.
[5] M. Bohner and A. Peterson, Advances in Dynamic Equations on Time Scales. Birkhäuser, Boston 2003.
[6] M. Cecchi, Z. Došlá and M. Marini, Half-linear equations and characteristic properties of principal solutions. J. Differential Equ. 208 (2005), 494-507; Corrigendum, J. Differential Equ. 221 (2006), 272-274.
[7] M. Cecchi, Z. Došlá and M. Marini, Half-linear differential equations with oscillating coefficient. Differential Integral Equ. 18 (2005), 1243-1246.
[8] M. Cecchi, Z. Došlá and M. Marini, Nonoscillatory half-linear difference equations and recessive solutions. Adv. Difference Equ. 2005:2 (2005), 193-204.
[9] M. Cecchi, Z. DošLÁ and M. Marini, Limit and integral properties of principal solutions for half-linear differential equations. Arch. Math. (Brno) 43 (2007), 75-86.
[10] O. Došlý and Á. Elbert, Integral characterization of principal solution of halflinear differential equations, Studia Sci. Math. Hungar. 36 (2000), 455-469.
[11] Z. Došlá and O. Došlý, Principal solution of half-linear differential equation: Limit and integral characterization. EJQTDE, Proc. 8th Coll. QTDE No. 7 (2008), 1-14.
[12] O. DošĹ́ AND S. FIŠNAROVÁ, Summation characterization of the recessive solution for half-linear difference equations. Submitted, 2009.
[13] H. Hoshino, R. Imabayashi, T. Kusano, T. Tanigawa, On second-order halflinear oscillations, Adv. Math. Sci. Appl. 8 (1), (1998), 199-216.
[14] P. Řehák, Half-linear dynamic equations on time scales: IVP and oscillatory properties. Nonlinear Funct. Anal. \& Appl. 7 (2002), 361-403.
[15] P. Řehák, Peculiarities in Power Type Comparison Results for Half-linear Dynamic Equations. Submitted, 2009.
[16] C. Pötzsche, Chain rule and invariance principle on measure chains. J. Comput. Appl. Math., 2001. Special issue on "Dynamic Equations on Time Scales", edited by R. P. Agarwal, M. Bohner and D. O'Regan.


[^0]:    *E-mail address: akine@mst.edu
    ${ }^{\dagger}$ E-mail address: dosla@math.muni.cz

