

Lecture 18:

Linear momentum and energy. Center of mass motion.

- Multi-step problems
- Elastic Collisions
- Center of mass motion
- Rocket propulsion

Momentum and energy in multi-step problems

In a quick collision:

- total linear momentum is conserved $\vec{P}_f = \vec{P}_i$
- total mechanical energy is usually **NOT** conserved

$$E_f \neq E_i$$

Before or after collision:

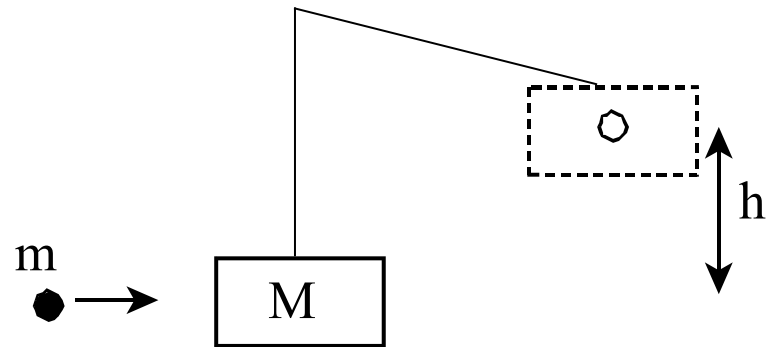
Mechanical energy may be conserved, or change in mechanical energy may be obtained from

$$E_f - E_i = W_{other}$$

Example: Ballistic pendulum

A bullet of mass m and unknown speed is fired into a block of mass M that is hanging from two cords. The bullet gets stuck in the block, and the block rises a height h .

What was the initial speed of the bullet?



Energy in collisions

In a quick collision:

- total linear momentum is conserved $\vec{P}_f = \vec{P}_i$
- total mechanical energy is usually **NOT** conserved

$$E_f \neq E_i$$

because non-conservative forces act (deforming metal)

→ **Inelastic** collision

Perfectly inelastic: objects stick together after collision

Elastic collision: mechanical energy is conserved

Elastic collisions

Mechanical energy is conserved if only conservative forces act during the collision.

Total linear momentum conserved: $\vec{P}_f = \vec{P}_i$

Total mechanical energy conserved: $E_f = E_i$

Example: elastic head-on collision with stationary target

x-component of momentum conservation:

$$p_{1ix} + p_{2ix} = p_{1fx} + p_{2fx}$$
$$m_1 v_1 = m_1 v_{f1x} + m_2 v_{f2x}$$

Energy conservation:

$$E_f = E_i$$
$$\frac{1}{2}m_1 v_{f1}^2 + \frac{1}{2}m_2 v_{f2}^2 = \frac{1}{2}m_1 v_1^2$$

After some algebra:

$$v_{f1x} = \frac{m_1 - m_2}{m_1 + m_2} v_1$$

$$v_{f2x} = \frac{2m_1}{m_1 + m_2} v_1$$

Special cases:

- | | |
|---------------|--|
| $m_1 \ll m_2$ | Ping-pong ball hits stationary cannon ball |
| $m_1 \gg m_2$ | Cannon ball hits ping-pong ball |
| $m_1 = m_2$ | Newton's cradle |

$$v_{f1x} = \frac{m_1 - m_2}{m_1 + m_2} v_1$$

$$v_{f2x} = \frac{2m_1}{m_1 + m_2} v_1$$

$m_1 \ll m_2$ Ping-pong ball hits stationary cannon ball

$m_1 \gg m_2$ Cannon ball hits ping-pong ball

$m_1 = m_2$ Newton's cradle

[Rosencrantz and Guildenstern are dead](#)

General elastic collisions:
two-dimensional, off-center,
particles move away at angles

3 equations:

x -component of Momentum Conservation:

$$P_{fx} = P_{ix}$$

y -component of Momentum Conservation:

$$P_{fy} = P_{iy}$$

Conservation of mechanical energy:

$$E_f = E_i$$

Center of Mass: Definition

$$M_{tot}\vec{r}_{CM} = \sum_n m_n\vec{r}_n$$

$$X_{CM} = \frac{1}{M_{tot}} \sum_n m_n x_n$$

$$Y_{CM} = \frac{1}{M_{tot}} \sum_n m_n y_n$$

Continuous object: integration

If object has line of symmetry: CM lies on it.

Same amount of mass on both sides.

Center of Mass: Example

$$X_{CM} = \frac{1}{M_{tot}} \sum_n m_n x_n$$

Center of mass and momentum

$$M_{tot} \vec{r}_{CM} = \sum_n m_n \vec{r}_n$$

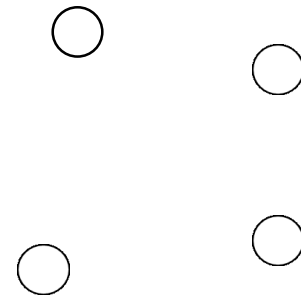
$$M_{tot} \frac{d\vec{r}_{CM}}{dt} = M_{tot} \vec{v}_{CM} = \sum_n m_n \vec{v}_n = \sum_n \vec{p}_n = \vec{P}$$

$$M_{tot} \frac{d\vec{v}_{CM}}{dt} = M_{tot} \vec{a}_{CM} = \frac{d\vec{P}}{dt} = \sum \vec{F}$$

Center of mass and external forces

$$M_{tot} \vec{a}_{CM} = \frac{d\vec{P}}{dt} = \sum \vec{F}$$

Particles in system interact
Internal forces occur in
action-reaction pairs, cancel.
Only external forces remain.

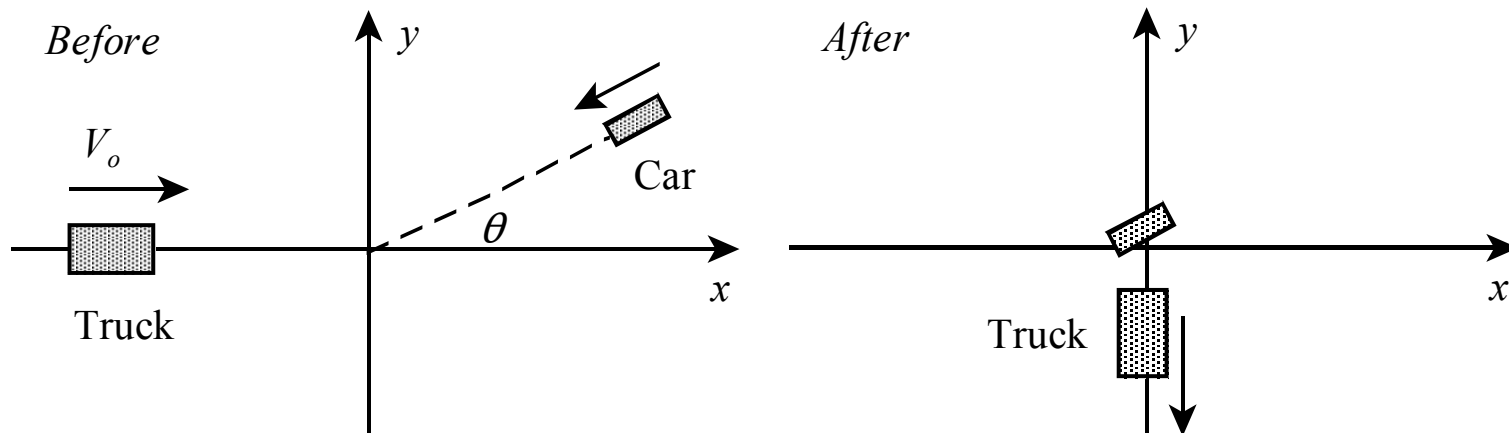


$$\sum \vec{F}_{ext} = M_{tot} \vec{a}_{CM}$$

[Demo: Center-of-mass motion](#)

Discussion question

A truck is moving with velocity V_0 along the positive x -direction. It is struck by a car which had been moving towards it at an angle θ with respect to the x -axis. As a result of the collision, the car is brought to a stop and the truck ends up sliding in the negative y -direction. The truck is twice as heavy as the car. ([Example from last lecture](#)) Find the **x -component of the velocity of the center of mass of truck and car before the collision.**



Another discussion question

You find yourself in the middle of a frictionless frozen lake.
How do you get to the shore?

Throw something

Same principle as rocket motion

Demo: rocket cart