

MTH 204
Fall 2006
Exam 4

Name: Key

Section: B

Read the directions carefully.

**Write neatly in pencil and show all your work
(you will only get credit for what you put on paper).**

Please do not share calculators during the test.

Each question is worth 25 points

**You must calculate all eigenvalues and eigenvectors
by hand. The last page contains your Laplace tables.
If you have trouble during the test, feel free to ask me for
help.**

1. Use the Laplace transform to solve the integral equation $f(t) = t - \int_0^t (t-\tau)f(\tau)d\tau$.

$$\mathcal{L}\{f(t)\} = \mathcal{L}\{t\} - \mathcal{L}\left\{\int_0^t (t-\tau)f(\tau)d\tau\right\}$$

$$F(s) = \frac{1}{s^2} - \mathcal{L}\{f(t) * t\}$$

$$g(t-\tau) = t-\tau \\ \Rightarrow g(t) = t$$

$$= \frac{1}{s^2} - \mathcal{L}\{f(t)\} \mathcal{L}\{t\}$$

$$= \frac{1}{s^2} - \frac{F(s)}{s^2}$$

$$\Rightarrow F(s) + \frac{F(s)}{s^2} = \left(\frac{s^2+1}{s^2}\right)F(s) = \frac{1}{s^2}$$

$$F(s) = \frac{1}{s^2} \left(\frac{s^2}{s^2+1}\right) = \frac{1}{s^2+1}$$

$$\Rightarrow f(t) = \mathcal{L}^{-1}\{F(s)\} = \mathcal{L}^{-1}\left\{\frac{1}{s^2+1}\right\} = \sin(t)$$

2. Solve the following initial value problem $\vec{x}' = \begin{bmatrix} 5 & 3 \\ 3 & 5 \end{bmatrix} \vec{x}$, $\vec{x}(0) = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$.

Method 1: $0 = \det(A - \lambda I)$
 $= \lambda^2 - \text{Tr}A \lambda + \det A$
 $= \lambda^2 - 10\lambda + 25 - 9$
 $= \lambda^2 - 10\lambda + 16$
 $= (\lambda - 8)(\lambda - 2)$

$\Rightarrow \lambda_1 = 8, \lambda_2 = 2$

For $\lambda_1 = 8$, $(A - \lambda_1 I) \vec{K}_1 = \vec{0}$

$$\begin{bmatrix} 5-8 & 3 & | & 0 \\ 3 & 5-8 & | & 0 \end{bmatrix} \Rightarrow \begin{bmatrix} -3 & 3 & | & 0 \\ 3 & -3 & | & 0 \end{bmatrix}$$

$\Rightarrow -k_1 + k_2 = 0$

$\Rightarrow k_1 = k_2$
 $\hookrightarrow FV = 1$

$\Rightarrow \vec{K}_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$

$\Rightarrow \vec{x}_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^{8t}$

GS: $\vec{x}(t) = c_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^{8t} + c_2 \begin{bmatrix} 1 \\ -1 \end{bmatrix} e^{2t}$

$\vec{x}(0) = \begin{bmatrix} 1 \\ -1 \end{bmatrix} = c_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} + c_2 \begin{bmatrix} 1 \\ -1 \end{bmatrix}$

$\Rightarrow \begin{matrix} c_1 + c_2 = 1 \\ c_1 - c_2 = -1 \end{matrix}$

 $2c_1 = 0 \Rightarrow c_1 = 0$
 $\Rightarrow c_2 = 1$

So $\vec{x}(t) = \begin{bmatrix} 1 \\ -1 \end{bmatrix} e^{2t}$

For $\lambda_2 = 2$, $(A - \lambda_2 I) \vec{K}_2 = \vec{0}$

$$\begin{bmatrix} 5-2 & 3 & | & 0 \\ 3 & 5-2 & | & 0 \end{bmatrix} \Rightarrow \begin{bmatrix} 3 & 3 & | & 0 \\ 3 & 3 & | & 0 \end{bmatrix}$$

$\Rightarrow k_1 + k_2 = 0$

$\Rightarrow k_2 = -k_1$
 $\hookrightarrow FV = 1$

$\Rightarrow \vec{K}_2 = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$

$\Rightarrow \vec{x}_2 = \begin{bmatrix} 1 \\ -1 \end{bmatrix} e^{2t}$

Method 2: $x' = 5x + 3y$
 $y' = 3x + 5y$

$$x(0) = 1$$
$$y(0) = -1$$

$$\begin{cases} \mathcal{L}\{x' - 5x - 3y\} = 0 \\ \mathcal{L}\{-3x + y' - 5y\} = 0 \end{cases}$$

$$\begin{cases} sX(s) - x(0) - 5X(s) - 3Y(s) = 0 \\ -3X(s) + sY(s) - y(0) - 5Y(s) = 0 \end{cases}$$

$$3[(s-5)X(s) - 3Y(s) = 1]$$
$$+(s-5)[-3X(s) + (s-5)Y(s) = -1]$$

$$\frac{(-9 + (s-5)^2)Y(s) = 3 - (s-5)}$$

$$(s-8)(s-2)Y(s) = -(s-8)$$

$$Y(s) = \frac{-1}{s-2}$$

$$\Rightarrow y(t) = -e^{2t}$$

$$(s-5)[(s-5)X(s) - 3Y(s) = 1]$$
$$+ 3[-3X(s) + (s-5)Y(s) = -1]$$

$$\frac{((s-5)^2 - 9)X(s) = s-5-3}$$

$$(s-2)(s-8)X(s) = s-8$$

$$X(s) = \frac{1}{s-2}$$

$$\Rightarrow x(t) = e^{2t}$$

$$\text{Then } \vec{x}(t) = \begin{bmatrix} x(t) \\ y(t) \end{bmatrix}$$
$$= \begin{bmatrix} 1 \\ -1 \end{bmatrix} e^{2t}$$

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3. Find the general solution to the following homogeneous linear system $\vec{x}' = \begin{bmatrix} 3 & -4 \\ 1 & -1 \end{bmatrix} \vec{x}$.

$$0 = \det(A - \lambda I) = \lambda^2 - \text{Tr} A \lambda + \det A = \lambda^2 - 2\lambda - 3 + 4 = (\lambda - 1)^2$$

$$\Rightarrow \lambda = 1, 1$$

$$(A - \lambda I) \vec{k} = \vec{0}$$

$$\begin{bmatrix} 3-1 & -4 & | & 0 \\ 1 & -1 & | & 0 \end{bmatrix} \Rightarrow \begin{bmatrix} 2 & -4 & | & 0 \\ 1 & -2 & | & 0 \end{bmatrix}$$

$$\Rightarrow k_1 - 2k_2 = 0$$

$$\Rightarrow k_1 = 2k_2$$

$\hookrightarrow \text{FV} = 1$

$$\Rightarrow \vec{k} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

$$\Rightarrow \vec{x}_1 = \begin{bmatrix} 2 \\ 1 \end{bmatrix} e^t$$

$$(A - \lambda I) \vec{p} = \vec{k}$$

$$\begin{bmatrix} 3-1 & -4 & | & 2 \\ 1 & -1 & | & 1 \end{bmatrix} \Rightarrow \begin{bmatrix} 2 & -4 & | & 2 \\ 1 & -2 & | & 1 \end{bmatrix}$$

$$\Rightarrow p_1 - 2p_2 = 1$$

$$\Rightarrow p_1 = 1 + 2p_2$$

$$\Rightarrow \vec{p} = \begin{bmatrix} 1 + 2p_2 \\ p_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix} + p_2 \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

Let $p_2 = 0$

$$\Rightarrow \vec{p} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$\Rightarrow \vec{x}_2 = \begin{bmatrix} 2 \\ 1 \end{bmatrix} t e^t + \begin{bmatrix} 1 \\ 0 \end{bmatrix} e^t$$

$$\text{GS: } \vec{x}(t) = c_1 \vec{x}_1 + c_2 \vec{x}_2$$

$$= c_1 \begin{bmatrix} 2 \\ 1 \end{bmatrix} e^t + c_2 \left(\begin{bmatrix} 2 \\ 1 \end{bmatrix} t e^t + \begin{bmatrix} 1 \\ 0 \end{bmatrix} e^t \right)$$

4. Find the general solution to the following homogeneous linear system $\vec{x}' = \begin{bmatrix} -1 & 1 \\ -5 & 3 \end{bmatrix} \vec{x}$.

$$0 = \det(A - \lambda I) = \lambda^2 - \text{Tr}A\lambda + \det A = \lambda^2 - 2\lambda - 3 + 5 = \lambda^2 - 2\lambda + 2$$

$$\Rightarrow \lambda = \frac{2 \pm \sqrt{4 - 4(2)}}{2} = \frac{2 \pm 2i}{2} = 1 \pm i$$

$$\text{Let } \lambda = 1 + i \Rightarrow (A - \lambda I) \vec{K} = \vec{0}$$

$$\begin{bmatrix} -1 - (1+i) & 1 \\ -5 & 3 - (1+i) \end{bmatrix} \begin{vmatrix} 0 \\ 0 \end{vmatrix} \Rightarrow \begin{bmatrix} -(2+i) & 1 & | & 0 \\ -5 & 2-i & | & 0 \end{bmatrix}$$

$$\Rightarrow -(2+i)k_1 + k_2 = 0$$

$$\Rightarrow k_2 = (2+i)k_1$$

$\hookrightarrow \text{FV} = 1$

$$\Rightarrow \vec{K} = \begin{bmatrix} 1 \\ 2+i \end{bmatrix}$$

$$z = \vec{K} e^{\lambda t} = \left(\begin{bmatrix} 1 \\ 2 \end{bmatrix} + i \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right) e^{(1+i)t} = \left(\begin{bmatrix} 1 \\ 2 \end{bmatrix} + i \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right) e^t (\cos(t) + i \sin(t))$$

$$= \begin{bmatrix} 1 \\ 2 \end{bmatrix} e^t \cos(t) + i \begin{bmatrix} 1 \\ 2 \end{bmatrix} e^t \sin(t) + i \begin{bmatrix} 0 \\ 1 \end{bmatrix} e^t \cos(t) - \begin{bmatrix} 0 \\ 1 \end{bmatrix} e^t \sin(t)$$

$$\vec{x}_1 = \text{Re } \vec{z} = \begin{bmatrix} 1 \\ 2 \end{bmatrix} e^t \cos(t) - \begin{bmatrix} 0 \\ 1 \end{bmatrix} e^t \sin(t) = \begin{bmatrix} \cos(t) \\ 2\cos(t) - \sin(t) \end{bmatrix} e^t$$

$$\vec{x}_2 = \text{Im } \vec{z} = \begin{bmatrix} 1 \\ 2 \end{bmatrix} e^t \sin(t) + \begin{bmatrix} 0 \\ 1 \end{bmatrix} e^t \cos(t) = \begin{bmatrix} \sin(t) \\ 2\sin(t) + \cos(t) \end{bmatrix} e^t$$

$$\text{GS: } \vec{x}(t) = c_1 \vec{x}_1 + c_2 \vec{x}_2$$

$$= c_1 \begin{bmatrix} \cos(t) \\ 2\cos(t) - \sin(t) \end{bmatrix} e^t + c_2 \begin{bmatrix} \sin(t) \\ 2\sin(t) + \cos(t) \end{bmatrix} e^t$$

Bonus (15 points): Use the Laplace transform to solve the following system of IVPs

$$\begin{cases} \frac{d^2x}{dt^2} + \frac{d^2y}{dt^2} = t^2 \\ \frac{d^2x}{dt^2} - \frac{d^2y}{dt^2} = 3t \end{cases} \quad \text{subject to } \begin{cases} x(0) = -1 & y(0) = 0 \\ x'(0) = 0 & y'(0) = 0 \end{cases}$$

$$\mathcal{L}\{x'' + y''\} = \mathcal{L}\{t^2\}$$

$$\mathcal{L}\{x'' - y''\} = 3\mathcal{L}\{t\}$$

$$\begin{cases} s^2X(s) - sx(0) - x'(0) + s^2Y(s) - sy(0) - y'(0) = \frac{2}{s^3} \\ s^2X(s) - sx(0) - x'(0) - (s^2Y(s) - sy(0) - y'(0)) = \frac{3}{s^2} \end{cases}$$

$$s^2X(s) + s^2Y(s) = \frac{2}{s^3} - s$$

$$+ s^2X(s) - s^2Y(s) = \frac{3}{s^2} - s$$

$$\underline{2s^2X(s) = \frac{2}{s^3} + \frac{3}{s^2} - 2s}$$

$$X(s) = \frac{1}{s^5} + \frac{3/2}{s^4} - \frac{1}{s}$$

$$x(t) = \frac{1}{4!} \mathcal{L}^{-1}\left\{\frac{4!}{s^{4+1}}\right\} + \frac{3}{2(3!)} \mathcal{L}^{-1}\left\{\frac{3!}{s^{3+1}}\right\} - \mathcal{L}^{-1}\left\{\frac{1}{s}\right\} = \frac{1}{24}t^4 + \frac{1}{4}t^3 - 1$$

$$s^2X(s) + s^2Y(s) = \frac{2}{s^3} - s$$

$$- s^2X(s) - s^2Y(s) = \frac{3}{s^2} - s$$

$$\underline{2s^2Y(s) = \frac{2}{s^3} - \frac{3}{s^2}}$$

$$Y(s) = \frac{1}{s^5} - \frac{3/2}{s^4} \quad \Rightarrow \quad y(t) = \frac{1}{24}t^4 - \frac{1}{4}t^3$$

$$\text{So } \begin{cases} x(t) = \frac{1}{24}t^4 + \frac{1}{4}t^3 - 1 \\ y(t) = \frac{1}{24}t^4 - \frac{1}{4}t^3 \end{cases}$$