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> Oscillation Criteria for Fourth-Order Nonlinear Dynamic Equations

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#### Abstract

Some oscillatory criteria for fourth order difference and differential equations are generalized to arbitrary time scales.

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#### 1 Introduction

This paper is concerned with the oscillatory behavior of fourth-order nonlinear dynamic equations

$$(p(t)(x^{\Delta^{2}})^{\alpha})^{\Delta^{2}}(t) + q(t)f(x^{\sigma})(t) = 0, \ t \in \mathbb{T}$$
(1)

where  $\alpha$  is the ratio of two positive odd integers,  $p, q \in C_{rd}(\mathbb{T}, \mathbb{R}^+)$ , and  $f \in C(\mathbb{R}, \mathbb{R})$  such that xf(x) > 0 and  $f'(x) \ge 0$  for  $x \ne 0$ .

A time scale  $\mathbb{T}$  is a nonempty closed subset of real numbers. The delta-derivative  $f^{\Delta}$  for a function f defined on  $\mathbb{T}$  turns out to be  $f^{\Delta} = f'$  (the usual derivative) if  $\mathbb{T} = \mathbb{R}$  and  $f^{\Delta} = \Delta f$  (the usual forward difference operator) if  $\mathbb{T} = \mathbb{Z}$ . Here  $\sigma : \mathbb{T} \to \mathbb{T}$  is the forward jump operator which gives the next point in  $\mathbb{T}$ . The study of dynamic equations on time scales is a fairly new topic, and work in this area is rapidly growing. It is introduced well in the fundamental texts by M. Bohner and A. Peterson in [8, 9]. For recent contributions concerning the oscillation of differential, difference and dynamic equations, see the books [2, 3, 4, 5, 8, 9] and the papers [1, 10, 11, 12, 13, 15, 16].

The main purpose of this paper is to pursue a systematic study for the oscillation of equation (1). For that reason, we assume that

$$\int^{\infty} p^{-\frac{1}{\alpha}}(t) \Delta t = \infty$$
<sup>(2)</sup>

and there exists a strictly increasing function  $\beta : \mathbb{T} \to \mathbb{T}$  such that  $\beta^2(\mathbb{T}) := \beta(\beta(\mathbb{T}))$  is a time scale,  $t < \beta(t)$  for all  $t \in \mathbb{T}$  and  $\beta^2$  is delta-differentiable. In Section 2, we prove a crucial lemma and give some preliminary results. In Section 3, we obtain the oscillation criteria for (1) as well as for special cases of (1) depending on  $\alpha \geq 1$  and  $\alpha < 1$ . Finally, we establish the oscillation criteria for some delay equations in the last section.

Throughout we assume that  $\mathbb{T}$  is an unbounded time scale. For convenience of notation, we let  $[t_0, \infty)_{\mathbb{T}} = [t_0, \infty) \cap \mathbb{T}$ ,  $t_0 \in \mathbb{T}$ , and  $x^{\Delta^2} = x^{\Delta\Delta}$ . By  $\mathcal{C}(M, N)$  ( $\mathcal{C}_{rd}(M, N)$ ) we mean the set of all continuous (right-dense continuous) functions defined on the set M to the set N. We denote  $\tau = \beta^2$ . We introduce the operators  $L_i, i = 0, 1, 2, 3, 4$ , as follows:

$$L_0 x = x, \ L_1 x = (L_0 x)^{\Delta}, \ L_2 x = p\{(L_1 x)^{\Delta}\}^{\alpha}, \ L_3 x = (L_2 x)^{\Delta}, \ L_4 x = (L_3 x)^{\Delta}.$$
 (3)

We recall that a solution of equation (1) is said to be *oscillatory* on  $[t_0, \infty)_{\mathbb{T}}$  in case it is neither eventually positive nor eventually negative. Otherwise, it is said to be *nonoscillatory*. Equation (1) is said to be *oscillatory* in case all of its solutions are oscillatory.

#### 2 Preliminaries

In this section, we first discuss possible sign conditions for the operators defined in (3) in case a solution of (1) is eventually positive. Then we obtain a crucial lemma. We finish this section with some preliminary results.

If x is an eventually positive solution of (1), then  $L_4x(t) < 0$  eventually. Since (2) holds, it follows that  $L_ix(t)$ , i = 1, 2, 3, are eventually of one sign. There are eight different sign combinations for these functions. It is easy to show that it is not possible that  $L_ix(t) > 0$ ,  $L_{i+1}x(t) < 0$ ,  $L_{i+2}x(t) < 0$  and  $L_ix(t) < 0$ ,  $L_{i+1}x(t) > 0$ ,  $L_{i+2}x(t) > 0$  for  $i \in \{0, 1, 2\}$ , see [7]. There are only two possibilities left, namely

(I) 
$$L_0x(t) > 0$$
,  $L_1x(t) > 0$ ,  $L_2x(t) > 0$ ,  $L_3x(t) > 0$ , and  $L_4x(t) < 0$  for  $t \ge t_0$ ;

(II)  $L_0x(t) > 0$ ,  $L_1x(t) > 0$ ,  $L_2x(t) < 0$ ,  $L_3x(t) > 0$ , and  $L_4x(t) < 0$  for  $t \ge t_0$ ,

where  $t_0$  is sufficiently large enough.

Case (I). Suppose  $L_0x(t) > 0$ ,  $L_1x(t) > 0$ ,  $L_2x(t) > 0$ ,  $L_3x(t) > 0$ , and  $L_4x(t) < 0$  for  $t \ge t_0$ . Since  $L_3x(t) > 0$  is decreasing for  $t \ge t_0$ , we get

$$L_2 x(t) - L_2 x(t_0) = \int_{t_0}^t L_3 x(s) \Delta s,$$

hence

$$p(t)\{(L_1x)^{\Delta}\}^{\alpha}(t) \ge (t-t_0)L_3x(t),$$

thus

$$x^{\Delta^{2}}(t) \ge \left(\frac{t-t_{0}}{p(t)}\right)^{\frac{1}{\alpha}} L_{3}^{\frac{1}{\alpha}} x(t) \text{ for } t \ge t_{0}.$$
(4)

Integrating (4) from  $t_0$  to t, using (I) and the decreasing property of  $L_3x(t)$ ,  $t \ge t_0$ , we obtain

$$x^{\Delta}(t) \ge L_3^{\frac{1}{\alpha}} x(t) \int_{t_0}^t \left(\frac{s-t_0}{p(s)}\right)^{\frac{1}{\alpha}} \Delta s \text{ for } t \ge t_0,$$

and repeating the same process yields

$$x(t) \ge L_3^{\frac{1}{\alpha}} x(t) \int_{t_0}^t \left( \int_{t_0}^u \left( \frac{s - t_0}{p(s)} \right)^{\frac{1}{\alpha}} \Delta s \right) \Delta u \quad \text{for } t \ge t_0.$$

Case (II). Suppose  $L_0x(t) > 0$ ,  $L_1x(t) > 0$ ,  $L_2x(t) < 0$ ,  $L_3x(t) > 0$ , and  $L_4x(t) < 0$  for  $t \ge t_0$ . From  $\sup \mathbb{T} = \infty$ , we see that there exists an increasing function  $\beta : \mathbb{T} \to \mathbb{T}$  such that  $t < \beta(t)$  for all  $t \in \mathbb{T}$ . Then note that  $L_3x(t) > 0$  is decreasing and  $L_2x(t) < 0$  for  $t \ge t_0$ . From

$$L_2 x(\beta(t)) - L_2 x(t) = \int_t^{\beta(t)} L_3 x(s) \Delta s,$$

we get that

$$-L_2 x(t) \ge (\beta(t) - t) L_3 x(\beta(t)),$$

which can be rewritten as

$$-x^{\Delta^2}(t) \ge \left(\frac{\beta(t)-t}{p(t)}\right)^{\frac{1}{\alpha}} L_3^{\frac{1}{\alpha}} x(\beta(t)).$$
(5)

Integrating (5) again from t to  $\beta(t)$ , we obtain

$$x^{\Delta}(t) \ge L_3^{\frac{1}{\alpha}} x(\beta^2(t)) \int_t^{\beta(t)} \left(\frac{\beta(s) - s}{p(s)}\right)^{\frac{1}{\alpha}} \Delta s,$$

and so

$$x(t) \geq L_3^{\frac{1}{\alpha}} x(\beta^2(t)) \int_{t_0}^t \int_s^{\beta(s)} \left(\frac{\beta(u)-u}{p(u)}\right)^{\frac{1}{\alpha}} \Delta u \Delta s.$$

For  $t \geq t_0$ , we set

$$h(t,t_0;p) := \min\left\{\int_{t_0}^t \left(\frac{s-t_0}{p(s)}\right)^{\frac{1}{\alpha}} \Delta s, \ \int_t^{\beta(t)} \left(\frac{\beta(s)-s}{p(s)}\right)^{\frac{1}{\alpha}} \Delta s\right\}$$

and

$$H(t, t_0; p) := \int_{t_0}^t h(s, t_0; p(s)) \Delta s.$$

Combining these inequalities, we obtain the following crucial lemma.

**Lemma 2.1** Let x(t) be a positive solution of (1) for  $t \ge t_0$ . Then, for all  $t \ge t_0$ ,

$$x^{\Delta}(t) \ge h(t, t_0; p) L_3^{\frac{1}{\alpha}} x(\tau(t))$$

and

$$x(t) \ge H(t, t_0; p) L_3^{\frac{1}{\alpha}} x(\tau(t)).$$

We also need the following lemma.

**Lemma 2.2** [14] If X and Y are nonnegative, then

$$X^{\lambda} - \lambda X Y^{\lambda - 1} + (\lambda - 1) Y^{\lambda} \ge 0, \ \lambda > 1,$$

where equality holds if and only if X = Y.

The following chain rule is extracted from [13] and plays an important role in this paper.

**Lemma 2.3** Assume that  $\tau : \mathbb{T} \to \mathbb{R}$  is strictly increasing and  $\tilde{\mathbb{T}} := \tau(\mathbb{T}) \subset \mathbb{T}$  is a time scale such that  $\tau \circ \sigma = \sigma \circ \tau$ . Let  $x : \tilde{\mathbb{T}} \to \mathbb{R}$ . If  $\tau^{\Delta}(t)$  and  $x^{\Delta}(\tau(t))$  exist for  $t \in \mathbb{T}^{\kappa}$ , then  $(x \circ \tau)^{\Delta}(t)$  exists, and  $(x \circ \tau)^{\Delta}(t) = x^{\Delta}(\tau(t))\tau^{\Delta}(t)$ .

From Remarks 4.1 and 4.2 in [6], we have the following result.

Lemma 2.4 Assume  $x \in C_{rd}([t_0, \infty)_{\mathbb{T}}, \mathbb{R})$ .

(i) If x(t) > 0,  $x^{\Delta}(t) \le 0$  on  $[t_0, \infty)_{\mathbb{T}}$  and  $\lambda < 1$ , then

$$\int_{t}^{\infty} \frac{-x^{\Delta}(s)}{x^{\lambda}(s)} \Delta s < \infty, \ t \in [t_0, \infty)_{\mathbb{T}};$$

(ii) If x(t) > 0,  $x^{\Delta}(t) \ge 0$  on  $[t_0, \infty)_{\mathbb{T}}$  and  $\lambda > 1$ , then

$$\int_{t}^{\infty} \frac{x^{\Delta}(s)}{(x^{\sigma}(s))^{\lambda}} \Delta s < \infty, \ t \in [t_0, \infty)_{\mathbb{T}}.$$

## **3** Oscillation Criteria for (1)

Throughout this paper, we assume  $\tau \circ \sigma = \sigma \circ \tau$ . In what follows we assume that

$$f^{\frac{1}{\alpha}-1}(u)g(u,v) \ge k > 0 \text{ for } u, v \ne 0,$$
(6)

where k is a constant and

$$g(u,v) = \int_0^1 f'(hu + (1-h)v)dh.$$
 (7)

**Theorem 3.1** Assume that (2), (6) and (7) hold, and there exists a function  $r : [t_0, \infty)_{\mathbb{T}} \to \mathbb{R}^+$  such that

$$\limsup_{t \to \infty} \int_{t_0}^t \left[ r(s)q(\tau(s))\tau^{\Delta}(s) - \left(\frac{1}{k^{\alpha}} \frac{\alpha^{\alpha}}{(1+\alpha)^{1+\alpha}} \frac{(r^{\Delta}(t))^{1+\alpha}}{(r(t)h(t,t_0;p))^{\alpha}} \right) \right] \Delta s = \infty,$$

where  $h(t, t_0; p)$  is defined as in Lemma 2.1. Then equation (1) is oscillatory.

*Proof:* Let x be an eventually positive solution of (1), say x(t) > 0 for all  $t \ge t_0$ ,  $t_0 \in \mathbb{T}$ . Then from (1), we see that  $L_4x(t) < 0$  for all  $t \ge t_0$  and hence  $L_ix(t)$ , i = 1, 2, 3, are eventually of one sign for all  $t \ge t_0$ . From the earlier argument in Section 2,  $L_3x(t) > 0$  is decreasing and  $L_1x(t) > 0$  for all  $t \ge t_1 \ge t_0$ ,  $t_1 \in \mathbb{T}$ . By Lemma 2.1, there exists  $t_2 \ge t_1$ ,  $t_2 \in \mathbb{T}$  such that

$$x^{\Delta}(t) \ge h(t, t_2; p) L_3^{\frac{1}{\alpha}} x(\tau(t)) \text{ for } t \ge t_2.$$
 (8)

Define

$$w(t) = r(t) \frac{L_3 x(\tau(t))}{f(x(t))} \text{ for } t \ge t_2$$

Then by Lemma 2.3 and [8, Theorem 1.90], for  $t \ge t_0$ , we have

$$\begin{split} w^{\Delta}(t) &= r^{\Delta}(t) \frac{L_{3}x(\tau(\sigma(t)))}{f(x(\sigma(t)))} + r(t) \frac{[L_{3}x(\tau(t))]^{\Delta}f(x(t)) - L_{3}x(\tau(t))[f(x(t))]^{\Delta}}{f(x(t))f(x(\sigma(t)))} \\ &= r^{\Delta}(t) \frac{w^{\sigma}(t)}{r^{\sigma}(t)} - r(t) \frac{q(\tau(t))f(x^{\sigma}(\tau(t)))\tau^{\Delta}(t)f(x(t))}{f(x(t))f(x(\sigma(t)))} \\ &- r(t)L_{3}x(\tau(t)) \frac{x^{\Delta}(t)\int_{0}^{1} f'[(1-h)x(t) + hx^{\sigma}(t)]dh}{f(x(t))f(x(\sigma(t)))} \\ &\leq r^{\Delta}(t) \frac{w^{\sigma}(t)}{r^{\sigma}(t)} - r(t)q(\tau(t))\tau^{\Delta}(t) - r(t)L_{3}x(\tau(t))x^{\Delta}(t) \frac{g(x^{\sigma}(t),x(t))}{f(x(t))f(x(\sigma(t)))} \\ &\leq r^{\Delta}(t) \frac{w^{\sigma}(t)}{r^{\sigma}(t)} - r(t)q(\tau(t))\tau^{\Delta}(t) - kr(t)L_{3}x(\tau(t)) \frac{x^{\Delta}(t)}{f^{1+\frac{1}{\alpha}}(x(\sigma(t)))} \\ &\leq r^{\Delta}(t) \frac{w^{\sigma}(t)}{r^{\sigma}(t)} - r(t)q(\tau(t))\tau^{\Delta}(t) - kr(t)L_{3}^{1+\frac{1}{\alpha}}x(\tau(t))h(t,t_{2};p)\frac{1}{f^{1+\frac{1}{\alpha}}(x(\sigma(t)))} \\ &\leq r^{\Delta}(t) \frac{w^{\sigma}(t)}{r^{\sigma}(t)} - r(t)q(\tau(t))\tau^{\Delta}(t) - kr(t)h(t,t_{2};p)\frac{w^{1+\frac{1}{\alpha}}(\sigma(t))}{r^{1+\frac{1}{\alpha}}(x(\sigma(t)))}. \end{split}$$
(9)

 $\operatorname{Set}$ 

$$X = [kr(t)h(t, t_2; p)]^{\frac{\alpha}{\alpha+1}} \frac{w^{\sigma}(t)}{r^{\sigma}(t)}, \quad \lambda = \frac{\alpha+1}{\alpha} > 1$$

and

$$Y = \left(\frac{\alpha}{\alpha+1}\right)^{\alpha} \left(\frac{r^{\Delta}(t)}{r^{\sigma}(t)}\right)^{\alpha} \left\{ [kr(t)h(t,t_2;p)]^{-\frac{\alpha}{\alpha+1}} r^{\sigma}(t) \right\}^{\alpha}$$

in Lemma 2.2 to conclude that for  $t \ge t_3 > t_2, t_3 \in \mathbb{T}$ 

$$r^{\Delta}(t)\frac{w^{\sigma}(t)}{r^{\sigma}(t)} - kr(t)h(t, t_2; p)\frac{w^{1+\frac{1}{\alpha}}(\sigma(t))}{r^{1+\frac{1}{\alpha}}(\sigma(t))} \le \frac{1}{k^{\alpha}}\frac{\alpha^{\alpha}}{(1+\alpha)^{1+\alpha}}\frac{(r^{\Delta}(t))^{1+\alpha}}{(r(t)h(t, t_2; p))^{\alpha}},$$

and so

$$w^{\Delta}(t) \leq -r(t)q(\tau(t))\tau^{\Delta}(t) + \frac{1}{k^{\alpha}} \frac{\alpha^{\alpha}}{(1+\alpha)^{1+\alpha}} \frac{(r^{\Delta}(t))^{1+\alpha}}{(r(t)h(t,t_2;p))^{\alpha}}, \ t \geq t_3.$$
(10)

Integrating both of sides of (10) from  $t_3$  to  $t \ge t_3$ , we obtain

$$w(t) - w(t_3) \le -\int_{t_3}^t \left[ r(s)q(\tau(s))\tau^{\Delta}(s) - \left(\frac{1}{k^{\alpha}} \frac{\alpha^{\alpha}}{(1+\alpha)^{1+\alpha}} \frac{(r^{\Delta}(s))^{1+\alpha}}{(r(s)h(s,t_2;p))^{\alpha}}\right) \right] \Delta s \to -\infty \text{ as } t \to \infty$$

which contradicts the fact that w(t) > 0 for  $t \ge t_2$ .

Now let

$$Q(t) := \int_t^\infty q(\tau(s))\tau^{\Delta}(s)\Delta s \text{ and } Q^*(t) := r(t)Q(t).$$

For the next three results, we obtain the oscillation criteria for (1) and special cases of (1) depending on  $\alpha$ .

**Theorem 3.2** Let  $0 < \alpha \leq 1$  and assume that (2), (6) and (7) hold. If there exists a function  $r: [t_0, \infty)_{\mathbb{T}} \to \mathbb{R}^+$  such that  $Q^*(t) > 0$  and

$$\limsup_{t \to \infty} \int_{t_0}^t \left[ p(s)q(\tau(s))\tau^{\Delta}(s) - \frac{1}{4k} \frac{(r^{\Delta}(s))^2 Q^{1-\frac{1}{\alpha}}(\sigma(s))}{r(s)h(s,t_0;p)} \right] \Delta s = \infty,$$

where  $h(t, t_0; p)$  is defined as in Lemma 2.1, then equation (1) is oscillatory.

*Proof:* Let x be a nonoscillatory solution of equation (1), say x(t) > 0 for  $t \ge t_0, t_0 \in \mathbb{T}$ . Define

$$y(t) = \frac{L_3 x(\tau(t))}{f(x(t))} \quad \text{for } t \ge t_0.$$

Then, similar to the proof of Theorem 3.1, we have  $y^{\Delta}(t) \leq -q(\tau(t))\tau^{\Delta}(t)$ , and so  $y(t) \geq Q(t)$  for  $t \geq t_0$ . Next, we define

$$w(t) = r(t) \frac{L_3 x(\tau(t))}{f(x(t))}$$
 for  $t \ge t_0$ .

Then  $w(t) \ge r(t)Q(t) = Q^*(t), t \ge t_0$ . Proceeding as in the proof of Theorem 3.1, we obtain (9) for  $t \ge t_2, t_2 \in \mathbb{T}$ . Now, for  $t \ge t_3, t_3 \in \mathbb{T}, t_3 \ge t_2$  we obtain

$$\begin{split} w^{\Delta}(t) &\leq r^{\Delta}(t) \frac{w^{\sigma}(t)}{r^{\sigma}(t)} - r(t)q(\tau(t))\tau^{\Delta}(t) - kr(t)h(t,t_{2};p) \frac{w^{1+\frac{1}{\alpha}}(\sigma(t))}{r^{1+\frac{1}{\alpha}}(x(\sigma(t)))} \\ &\leq r^{\Delta}(t) \frac{w^{\sigma}(t)}{r^{\sigma}(t)} - r(t)q(\tau(t))\tau^{\Delta}(t) - kr(t)h(t,t_{2};p)r^{-1-\frac{1}{\alpha}}(\sigma(t))(Q^{*})^{\frac{1}{\alpha}-1}(\sigma(t))w^{2}(\sigma(t)) \\ &= -r(t)q(\tau(t))\tau^{\Delta}(t) + \frac{1}{4k} \frac{(r^{\Delta}(t))^{2}Q^{1-\frac{1}{\alpha}}(\sigma(t))}{r(t)h(t,t_{2};p)} \\ &- \left[\sqrt{kr(t)r^{-2}(\sigma(t))h(t,t_{2};p)Q^{\frac{1}{\alpha}-1}(\sigma(t))}w^{\sigma}(t) - \frac{r^{\Delta}(t)}{2r^{\sigma}(t)\sqrt{kr(t)r^{-2}(\sigma(t))h(t,t_{2};p)Q^{\frac{1}{\alpha}-1}(\sigma(t))}}\right]^{2} \\ &\leq -r(t)q(\tau(t))\tau^{\Delta}(t) + \frac{1}{4k} \frac{(r^{\Delta}(t))^{2}Q^{1-\frac{1}{\alpha}}(\sigma(t))}{r(t)h(t,t_{2};p)}. \end{split}$$

The rest of the proof is similar to that of Theorem 3.1 and hence omitted.

The following result is concerned with the oscillation of a special case of equation (1), namely, the equation

$$L_4(x(t)) + q(t)x^{\alpha}(\sigma(t)) = 0.$$
(11)

**Theorem 3.3** Let  $\alpha \geq 1$  and assume that (2) holds. If there exists a function  $r : [t_0, \infty)_{\mathbb{T}} \to \mathbb{R}^+$  such that

$$\limsup_{t \to \infty} \int_{t_0}^t \left[ p(s)q(\tau(s))\tau^{\Delta}(s) - \frac{(r^{\Delta}(t))^2}{4\alpha r(t)h^{\alpha}(t,t_0;p)(t-t_0)^{\alpha-1}} \right] \Delta s = \infty,$$

where  $h(t, t_0; p)$  is defined as in Lemma 2.1, then all bounded solutions of equation (11) are oscillatory.

*Proof:* Let x(t) be an eventually bounded positive solution of equation (11). It is easy to see that x(t) satisfies (II). Proceeding as in the proof of Theorem 3.1, we obtain (8) for  $t \ge t_2$ ,  $t_2 \in \mathbb{T}$ , and we can easily see that

$$x(t) \ge (t - t_2) x^{\Delta}(t), \ t \ge t_2.$$
 (12)

Define

$$w(t) = r(t) \frac{L_3(x(\tau(t)))}{x^{\alpha}(t)}, \ t \ge t_2.$$

By Lemma 2.3, we can show that  $[x^{\alpha}(t)]^{\Delta} \ge \alpha x^{\Delta}(t)x^{\alpha-1}(t)$ . Then from (8), for  $t \ge t_2$ , we have

$$\begin{split} w^{\Delta}(t) &= r^{\Delta}(t) \frac{L_{3}x(\tau(\sigma(t)))}{x^{\alpha}(\sigma(t))} + r(t) \frac{x^{\alpha}(t)(L_{3}x(\tau(t)))^{\Delta} - L_{3}x(\tau(t))(x^{\alpha}(t))^{\Delta}}{x^{\alpha}(t)x^{\alpha}(\sigma(t))} \\ &\leq \frac{r^{\Delta}(t)}{r^{\sigma}(t)} w^{\sigma}(t) - r(t)q(\tau(t))\tau^{\Delta}(t) - r(t)L_{3}x(\tau(t))\frac{(x^{\alpha}(t))^{\Delta}}{x^{\alpha}(t)x^{\alpha}(\sigma(t))} \\ &\leq \frac{r^{\Delta}(t)}{r^{\sigma}(t)} w^{\sigma}(t) - r(t)q(\tau(t))\tau^{\Delta}(t) - \alpha r(t)L_{3}x(\tau(t))(x^{\Delta}(t))^{\alpha}(x^{\Delta}(t))^{1-\alpha}\frac{x^{\alpha-1}(t)}{(x^{\alpha}(\sigma(t)))^{2}} \\ &\leq \frac{r^{\Delta}(t)}{r^{\sigma}(t)} w^{\sigma}(t) - r(t)q(\tau(t))\tau^{\Delta}(t) - \alpha \frac{r(t)}{r^{2}(\sigma(t))}h^{\alpha}(t,t_{2};p)\left(\frac{x(t)}{x^{\Delta}(t)}\right)^{\alpha-1} w^{2}(\sigma(t)). \end{split}$$

Using (12) in the above inequality, we get for  $t \ge t_3 > t_2, t_3 \in \mathbb{T}$ ,

$$\begin{split} w^{\Delta}(t) &\leq \frac{r^{\Delta}(t)}{r^{\sigma}(t)} w^{\sigma}(t) - r(t)q(\tau(t))\tau^{\Delta}(t) - \alpha \frac{r(t)}{r^{2}(\sigma(t))} (t - t_{2})^{\alpha - 1} h^{\alpha}(t, t_{2}; p) w^{2}(\sigma(t)) \\ &= -r(t)q(\tau(t))\tau^{\Delta}(t) + \frac{(r^{\Delta}(t))^{2}}{4\alpha r(t)h^{\alpha}(t, t_{0}; p)(t - t_{0})^{\alpha - 1}} \\ &- \left[ \sqrt{\alpha \frac{r(t)}{r^{2}(\sigma(t))}} h^{\alpha}(t, t_{2}; p)(t - t_{2})^{\alpha - 1}} w^{\sigma}(t) - \frac{r^{\Delta}(t)}{2r^{\sigma}(t)\sqrt{\alpha \frac{r(t)}{r^{2}(\sigma(t))}} h^{\alpha}(t, t_{2}; p)(t - t_{2})^{\alpha - 1}} \right]^{2} \\ &\leq - \left[ r(t)q(\tau(t))\tau^{\Delta}(t) - \frac{(r^{\Delta}(t))^{2}}{4\alpha r(t)h^{\alpha}(t, t_{0}; p)(t - t_{0})^{\alpha - 1}} \right]. \end{split}$$

The rest of the proof is similar to that of Theorem 3.1, and hence omitted.

The following result is concerned with the oscillation of another special case of equation (1), namely

$$L_4 x(t) + q(t) x^{\sigma}(t) = 0$$
(13)

**Theorem 3.4** Let  $\alpha < 1$ . In addition to (2) we assume that

$$\int^{\infty} q(\tau(t))\tau^{\Delta}(t)\Delta t < \infty.$$

and

$$\lim_{t \to \infty} \int_{t_0}^t h(s, t_0; p) Q^{\frac{1}{\alpha}}(\sigma(s)) \Delta s = \infty, \quad t_0 \in \mathbb{T}.$$
 (14)

Then equation (13) is oscillatory.

*Proof:* Let x(t) be an eventually positive solution of equation (13), say, x(t) > 0 for  $t \ge t_0$ . We define

$$w(t) = \frac{L_3 x(\tau(t))}{x(t)}.$$

Similar to the proof in Theorem 3.1, we obtain

$$\left(\frac{L_3x(\tau(t))}{x(t)}\right)^{\Delta} \le -q(\tau(t))\tau^{\Delta}(t), \ t \ge t_2.$$
(15)

Integrating (15) from  $\sigma(t)$  to u, we get

$$0 < \frac{L_3 x(\tau(u))}{x(u)} \le \frac{L_3 x(\tau(\sigma(t)))}{x(\sigma(t))} - \int_{\sigma(t)}^u q(\tau(s)) \tau^{\Delta}(s) \Delta s.$$

$$(16)$$

Letting  $u \to \infty$  in (16), we obtain

$$\frac{L_3 x(\tau(\sigma(t)))}{x(\sigma(t))} \ge Q(\sigma(t)). \tag{17}$$

Using (8) in (17) and noting that  $L_3x$  is decreasing, we find

$$\left(\frac{x^{\Delta}(t)}{x^{\frac{1}{\alpha}}(\sigma(t))}\right)^{\alpha} \ge h^{\alpha}(t, t_2; p)Q(\sigma(t)), \ t \ge t_2$$

or

$$h(t, t_2; p)Q^{\frac{1}{\alpha}}(\sigma(t)) \le \frac{x^{\Delta}(t)}{x^{\frac{1}{\alpha}}(\sigma(t))}, \ t \ge t_2$$

$$(18)$$

Integrating (18) from  $t_2$  to t, we get

$$\int_{t_2}^t h(s, t_2; p) Q^{\frac{1}{\alpha}}(\sigma(s)) \Delta s \le \int_{t_2}^t \frac{x^{\Delta}(s)}{x^{\frac{1}{\alpha}}(\sigma(s))} \Delta s.$$
(19)

Taking limit of both sides of (19) as  $t \to \infty$ , we arrive at the desired contradiction by Lemma 2.4 (ii) and (14).

## 4 Oscillation Criteria for Delay Dynamic Equations

We consider the delay dynamic equation

$$L_4 x(t) + q(t) f(x(\theta(t))) = 0, (20)$$

where  $\theta : \mathbb{T} \to \mathbb{T}$  is an increasing delay function satisfying  $\lim_{t \to \infty} \theta(t) = \infty$  and  $\theta(t) \le t$  for all  $t \in \mathbb{T}$  and we study the oscillation for delay dynamic equation (20). We first present some comparison criteria.

Lemma 4.1 Let (2) hold. If the inequality

$$L_4 x(t) + q(t) f(x(\theta(t))) \le 0 \tag{21}$$

has an eventually positive (negative) solution, then the equation (20) also has an eventually positive (negative) solution.

*Proof:* Let x(t) be an eventually positive solution of (21). There exists  $t_0 \in \mathbb{T}$  such that x(t) > 0 for  $t \ge t_0$  and x(t) satisfies either (I) or (II) for  $t \ge t_0$ . Integrating (21) from  $t \ge t_0$  to  $u \ge t$  and letting  $u \to \infty$ , we have

$$L_3 x(t) \ge \int_t^\infty q(s) f(x(\theta(s))) \Delta s.$$
(22)

Now, we need to distinguish the following two cases:

Case (I).  $L_i x(t) > 0$  for  $t \ge t_0$ , i = 0, 1, 2, 3. Integrating (22) from  $t_0$  to  $t \ge t_0$ , we get

$$L_2 x(t) \ge \int_{t_0}^t \int_s^\infty q(u) f(x(\theta(u))) \Delta u \Delta s$$

or

$$x^{\Delta^2}(t) \ge \left(\frac{1}{p(t)} \int_{t_0}^t \int_s^\infty q(u) f(x(\theta(u))) \Delta u \Delta s\right)^{\frac{1}{\alpha}}$$

and so,

$$x(t) \ge \int_{t_0}^t \int_{t_0}^{s_3} \left(\frac{1}{p(s_2)} \int_{t_0}^{s_2} \int_{s_1}^{\infty} q(s) f(x(\theta(s))) \Delta s \Delta s_1\right)^{\frac{1}{\alpha}} \Delta s_2 \Delta s_3.$$

Define

$$\Phi(t, x(\theta(t))) := \int_{t_0}^t \int_{t_0}^{s_3} \left( \frac{1}{p(s_2)} \int_{t_0}^{s_2} \int_{s_1}^{\infty} q(s) f(x(\theta(s))) \Delta s \Delta s_1 \right)^{\frac{1}{\alpha}} \Delta s_2 \Delta s_3 - c,$$

where  $c = x(t_0)$ . Now, we show that the existence of a positive solution to the equation

$$y(t) = c + \Phi(t, y(\theta(t)))$$
 for  $t \ge t_0$ .

In order to do this, we define the function sequence  $\{y_k(t)\}, k = 0, 1, \dots$ , such that

$$y_0(t) = x(t), \quad y_{k+1}(t) = c + \Phi(t, y_k(\theta(t))) \text{ for } t \ge t_0.$$
 (23)

Then, one can easily see that  $y_k(t)$  is well-defined and

$$0 \le y_k(t) \le x(t), \quad c \le y_{k+1}(t) \le y_k(t).$$

Thus,  $y_k$  is positive and nonincreasing in k for  $t \ge t_0$ . This means we may define  $y(t) = \lim_{k \to \infty} y_k(t)$ . Since  $0 < y(t) \le y_k(t) \le x(t)$  for all  $k \ge 0$  and

$$\Phi(t, y_k(\theta(t))) \le \Phi(t, x(\theta(t))),$$

the convergence of  $\{y_k(t)\}\$  is uniform with respect to t. Now, taking the limit of both sides of (23), we have

$$y(t) = c + \Phi(t, y(\theta(t))) \quad \text{for } t \ge t_0.$$

$$(24)$$

Finally, taking the delta derivative of (24) four times, we obtain

$$L_4 y(t) + q(t) f(y(\theta(t))) = 0.$$

Case (II).  $L_i x(t) > 0$ , i = 0, 1, 3 and  $L_2 x(t) < 0$  for  $t \ge t_0$ . Integrating (22) from  $t \ge t_0$  to u and letting  $u \to \infty$ , we have

$$-x^{\Delta^2}(t) \ge \left(\frac{1}{p(t)} \int_t^\infty \int_s^\infty q(u) f(x(\theta(u))) \Delta u \Delta s\right)^{\frac{1}{\alpha}}$$

Define

$$\Psi(t, x(\theta(t))) := \int_{t_0}^t \int_{s_3}^\infty \left(\frac{1}{p(s_2)} \int_{s_2}^\infty \int_{s_1}^\infty q(s) f(x(\theta(s))) \Delta s \Delta s_1\right)^{\frac{1}{\alpha}} \Delta s_2 \Delta s_3.$$

Then

$$x(t) \ge c + \Psi(t, x(\theta(t)))$$
 with  $c = x(t_0)$ 

The rest of the proof is similar to that of Case (I) and hence omitted.

Theorem 4.2 Let (2) hold. If

$$x^{\Delta^2}(t) + \left(\frac{1}{p(t)} \int_t^\infty \int_s^\infty q(u) \Delta u\right)^{\frac{1}{\alpha}} f^{\frac{1}{\alpha}}(x(\sigma(t)) = 0$$
(25)

is oscillatory, then all bounded solutions of equation (1) are oscillatory.

*Proof:* Let x(t) be a nonoscillatory bounded solution of equation (1), say, x(t) > 0 for  $t \ge t_0$ ,  $t_0 \in \mathbb{T}$ . It is easy to check that x(t) satisfies (II) for  $t \ge t_1 \ge t_0$ ,  $t_1 \in \mathbb{T}$ . Integrating equation (1) from  $t \ge t_1$  to u and letting  $u \to \infty$ , we have

$$L_3x(u) - L_3x(t) = -\int_t^u q(s)f(x^{\sigma}(s))\Delta s$$

and so

$$L_3 x(t) \ge \int_t^\infty q(s) f(x^{\sigma}(s)) \Delta s \ge f(x^{\sigma}(t)) \int_t^\infty q(s) \Delta s, \ t \ge t_1.$$
(26)

Once again, integrating (26) from  $t \ge t_1$  to u and letting  $u \to \infty$ , we obtain

$$-L_2 x(t) \ge f(x^{\sigma}(t)) \int_t^{\infty} \left( \int_s^{\infty} q(v) \Delta v \right) \Delta s, \ t \ge t_1$$

or

$$x^{\Delta^2}(t) + \left(\frac{1}{p(t)}\int_t^\infty (\int_s^\infty q(v)\Delta v)\Delta s\right)^{\frac{1}{\alpha}} f^{\frac{1}{\alpha}}(x^\sigma(t)) \le 0, \ t \ge t_1.$$

Similar to the proof of Case (II) in Lemma 4.1, we can show that (25) has an eventually positive solution, which contradicts the hypothesis and completes the proof.  $\Box$ 

By the similar method of proof in Lemma 4.1, we can show that the following comparison result.

Lemma 4.3 Let (2) hold. If

$$x^{\Delta}(t) + q(t)f(x(\theta(t)) \le 0,$$

has an eventually positive (negative) solution, then

$$x^{\Delta}(t) + q(t)f(x(\theta(t))) = 0$$

also has an eventually positive (negative) solution.

Now we establish some oscillation criteria for equation (20).

**Theorem 4.4** Let (2) hold and assume that f satisfies

$$-f(-xy) \ge f(xy) \ge f(x)f(y) \quad \text{for } xy > 0.$$

$$(27)$$

If

$$y^{\Delta}(t) + q(t)f(H(\theta(t), t_0; p))f(y^{\frac{1}{\alpha}}(\tau(\theta(t)))) = 0$$
(28)

is oscillatory, then equation (20) is oscillatory.

*Proof:* Let x(t) be a nonoscillatory solution of equation (20), say, x(t) > 0 for  $t \ge t_0$ ,  $t_0 \in \mathbb{T}$ , and x(t) satisfies (I) or (II). By Lemma 2.1, there exists  $t_1 \ge t_0$  so large that

$$x(\theta(t)) \ge H(\theta(t), t_0; p) L_3^{\frac{1}{\alpha}} x(\tau(\theta(t))) \text{ for } t \ge t_1, t_1 \in \mathbb{T}.$$
(29)

Using (29) and (27) in (20), we have

$$-(L_3 x(t))^{\Delta} \ge q(t) f(H(\theta(t)), t_0; p)) f(L_3^{\frac{1}{\alpha}} x(\tau(\theta(t)))), \ t \ge t_1$$

Substituting y(t) for  $L_3x(t)$ ,  $t \ge t_1$ , we get

$$-y^{\Delta}(t) \ge q(t)f(H(\theta(t)), t_0; p))f(y^{\frac{1}{\alpha}}(\tau(\theta(t)))), \ t \ge t_1$$

Note that x(t) satisfies (I) or (II) implies that y(t) > 0 for  $t \ge t_1$ . So (28) has an eventually positive solution by Lemma 4.3, which contradicts with the hypothesis and completes the proof.

We now present the following result for the oscillation of all bounded solutions of equation (20).

Theorem 4.5 Let (2) hold. If

$$\int_{t_0}^{\infty} \int_k^{\infty} \left(\frac{1}{p(\nu)} \int_{\nu}^{\infty} \int_{\tau}^{\infty} q(s) \Delta s \Delta \tau\right)^{\frac{1}{\alpha}} \Delta \nu \Delta k = \infty, \tag{30}$$

then all bounded solutions of equation (20) are oscillatory.

*Proof:* Let x(t) be a nonoscillatory bounded solutions of equation (20), say, x(t) > 0 for  $t \ge t_0$ . Clearly, x(t) satisfies (II) for  $t \ge t_1$  for some  $t_1 \ge t_0$ . Now, there exist a constant c > 0 and an  $t_2 \ge t_1$ ,  $t_2 \in \mathbb{T}$  such that

$$\frac{c}{2} \le x(\theta(t)) \le c \text{ for } t \ge t_2.$$
(31)

Using (31), we have

$$L_4 x(t) + q(t) f(\frac{c}{2}) \le 0 \text{ for } t \ge t_2.$$
 (32)

Integrating (32) from  $t \ge t_2$  to  $u \ge t$  and letting  $u \to \infty$ , we have

$$L_3 x(t) \ge f(\frac{c}{2}) \int_t^\infty q(s) \Delta s.$$
(33)

Once again, integrating (33) from  $t \ge t_2$  to  $u \ge t$  and letting  $u \to \infty$ , we get

$$-x^{\Delta^2}(t) \ge f^{\frac{1}{\alpha}}(\frac{c}{2}) \left(\frac{1}{p(t)} \int_t^\infty \int_\tau^\infty q(s) \Delta s \Delta \tau\right)^{\frac{1}{\alpha}}.$$

Therefore, we find

$$x(t) \ge x(t_1) + f^{\frac{1}{\alpha}}(\frac{c}{2}) \int_{t_2}^{\infty} \int_{k}^{\infty} \left(\frac{1}{p(\nu)} \int_{\nu}^{\infty} \int_{\tau}^{\infty} q(s) \Delta s \Delta \tau\right)^{\frac{1}{\alpha}} \Delta \nu \Delta k \to \infty \text{ as } t \to \infty,$$

which contradicts with (30) and completes the proof.

The following theorems are concerned with a necessary and sufficient condition for the oscillation of all bounded and unbounded solutions of

$$L_4 x(t) + q(t) x^{\gamma}(\theta(t)) = 0, \qquad (34)$$

where  $\gamma$  is the ratio of two positive odd integers.

**Theorem 4.6** Let  $\gamma > \alpha$  and condition (2) hold. Then all bounded solutions of equation (34) are oscillatory if and only if (30) holds.

*Proof:* Let x(t) be a nonoscillatory bounded solution of equation (34), say x(t) > 0 for  $t \ge t_0$ ,  $t_0 \in \mathbb{T}$ . Clearly, x(t) satisfies (II) for  $t \ge t_1$  for some  $t_1 \ge t_0$ ,  $t_1 \in \mathbb{T}$ . The proof of the "if" part is an immediate corollary of Theorem 4.5 and hence omitted.

Now, we prove the "only if" part of the theorem. Let c > 0 be a given arbitrary constant, and choose a large  $T \ge t_1, T \in \mathbb{T}$  such that

$$\int_{T}^{\infty} \int_{k}^{\infty} \left(\frac{1}{p(\nu)} \int_{\nu}^{\infty} \int_{\tau}^{\infty} q(s) \Delta s \Delta \tau\right)^{\frac{1}{\alpha}} \Delta \nu \Delta k \leq \frac{1}{2} c^{1-\frac{\gamma}{\alpha}}.$$

We introduce the Banach space  $\mathcal{A}$  of all bounded real-valued functions defined on  $[T, \infty)_{\mathbb{T}}$ with the norm  $||x|| = \sup_{t \in [T,\infty)_{\mathbb{T}}} |x(t)|$ . We define a bounded convex and closed subset  $\mathcal{B}$  of  $\mathcal{A}$ 

$$\mathcal{B} = \{ x \in \mathcal{A} : \frac{c}{2} \le x(\theta(t)) \le c, \ t \ge T \}.$$

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as

Next, let  $\mathcal{F}$  be a mapping defined on  $\mathcal{B}$  by

$$(\mathcal{F}x)(t) = c - \int_T^t \int_k^\infty \left(\frac{1}{p(\nu)} \int_\nu^\infty \int_\tau^\infty q(s) x^\gamma(\theta(s)) \Delta s \Delta \tau\right)^{\frac{1}{\alpha}} \Delta \nu \Delta k$$

It is now easy to show that  $\mathcal{F}$  maps  $\mathcal{B}$  into itself and  $\mathcal{F}$  is a continuous mapping. Also  $\mathcal{F}(\mathcal{B})$  is relatively compact in  $\mathcal{A}$ . Therefore, by Schauder fixed point theorem, there exists  $x \in \mathcal{B}$  such that  $x = \mathcal{F}x$ . It is clear that the fixed point x = x(t) gives a positive solution of (34) for  $t \geq T$ .

**Theorem 4.7** Let  $\gamma < \alpha$  and (2) hold. Then all unbounded solutions of (34) are oscillatory if and only if for all large  $t \ge t_0$ ,  $t_0 \in \mathbb{T}$ ,

$$\int^{\infty} q(t) H_1^{\gamma}(\theta(t), t_0; p) \Delta t = \infty, \qquad (35)$$

where

$$H_1(t,t_0;p) = \int_{t_0}^t \int_{t_0}^u \left(\frac{s-t_0}{p(s)}\right)^{\frac{1}{\alpha}} \Delta s \Delta u.$$

*Proof:* Let x(t) be an unbounded nonoscillatory solution of equation (34), say x(t) > 0 for  $t \ge t_0, t_0 \in \mathbb{T}$ . It is easy to see that x(t) satisfies (I), and so,

$$x(t) \ge H_1(t, t_0; p) L_3^{\frac{1}{\alpha}} x(t), \ t \ge t_1 \ge t_0, \ t_1 \in \mathbb{T}$$

Furthermore, we have

$$x^{\gamma}(\theta(t)) \ge H_1^{\gamma}(\theta(t), t_0; p) L_3^{\frac{\gamma}{\alpha}} x(\theta(t)) \ge H_1^{\gamma}(\theta(t), t_0; p) L_3^{\frac{\gamma}{\alpha}} x(t).$$
(36)

Using (36) in (34), we obtain

$$-L_4 x(t) \ge q(t) H_1^{\gamma}(\theta(t), t_0; p) L_3^{\frac{\gamma}{\alpha}} x(t).$$

Set  $y(t) = L_3 x(t)$ . Then

$$y^{\Delta}(t) + q(t)H_1^{\gamma}(\theta(t), t_0; p)y^{\frac{\gamma}{\alpha}}(t) \le 0.$$
 (37)

Dividing both sides of (37) by  $y^{\frac{\gamma}{\alpha}}(t)$  and integrating from  $t_1$  to u

$$\int_{t_1}^u q(t) H_1^{\gamma}(\theta(t), t_0; p) \Delta t \le - \int_{t_1}^u \frac{y^{\Delta}(t)}{y^{\frac{\gamma}{\alpha}}(t)} \Delta t.$$

By Lemma 2.4 (i) and as  $u \to \infty$ , we conclude that

$$\int_{t_1}^{\infty} q(t) H_1^{\gamma}(\theta(t), t_0; p) \Delta t \le \int_{t_1}^{\infty} \frac{-y^{\Delta}(t)}{y^{\frac{\gamma}{\alpha}}(t)} \Delta t < \infty,$$

which contradicts with (35).

To prove the "only if" part it suffices to assume that

$$\int_{0}^{\infty} q(s) H_{1}^{\gamma}(\theta(s), t_{0}; p) \Delta s < \infty,$$

and show the existence of a nonoscillatory solution of (34). Let c > 0 be an arbitrary constant and choose  $T > t_1 \ge t_0$ ,  $T \in \mathbb{T}$  sufficiently large so that

$$\int_T^\infty q(s) H_1^\gamma(\theta(s),t_0;p) \Delta s < c^{1-\frac{\alpha}{\gamma}}$$

Let X be the subset of all real-valued functions set  $X_1$  defined on  $[T,\infty)_{\mathbb{T}}$  by

$$X = \{x: c_1 H_1(t,T;p) \le x(t) \le c_2 H_1(t,T;p), t \ge T\},\$$

where  $c_1 = (\frac{c}{2})^{\frac{1}{\alpha}}$  and  $c_2 = (2c)^{\frac{1}{\alpha}}$ . Clearly, X is a closed, convex and compact subset of  $X_1$ . Let S be a mapping defined on X as follows: For  $x \in X$ ,

$$(Sx)(t) = \int_{T}^{t} \int_{T}^{k} \left( \frac{1}{p(\nu)} \left[ c(\nu - T) + \int_{T}^{\nu} \int_{\tau}^{\infty} q(s) x^{\gamma}(\theta(s)) \Delta s \Delta \tau \right] \right)^{\frac{1}{\alpha}} \Delta \nu \Delta k \text{ for } t \ge T.$$

$$(38)$$

It is easy to show that S is continuous and maps X into itself and relatively compact in  $X_1$ . Therefore, by Schauder fixed point theorem, S has a fixed point x in X which satisfies

$$x(t) = \int_{T}^{t} \int_{T}^{k} \left( \frac{1}{p(\nu)} \left[ c(\nu - T) + \int_{T}^{\nu} \int_{\tau}^{\infty} q(s) x^{\gamma}(\theta(s)) \Delta s \Delta \tau \right] \right)^{\frac{1}{\alpha}} \Delta \nu \Delta k \text{ for } t \ge T.$$
(39)

Taking the delta derivative four times on (39), we see that x = x(t) is a positive solution of (34) for  $t \ge T$ .

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