

BCD Arithmetic

Implementing the Decimal Adjust Command in WIMP51
CpE-213 Sp 2014 Project 1

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Abstract: The 8051 Microcontroller “decimal adjust” (DA) command was to be implemented for WIMP51. This function was to be programmed so that it could be called by the standard 8051 instruction byte. Moreover, the successful implementation would leave all other functionality of the processor unaffected.

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Introduction

The 8051 microcontroller has several functions not available in the WIMP51. One such function is “decimal adjust”, which converts single byte hexadecimal numbers to binary-coded decimal (BCD) and allows for decimal arithmetic to be performed on what are in fact binary numbers. The assembly level command for 8051’s decimal adjust is DA; and the machine code is D4H. For convenience, the 8051 instruction was retained in the WIMP51 implementation.

Description of Work

The majority of modifications to the WIMP51 affected only the arithmetic logic unit (ALU). The sole conflict between DA and the ripple carry adder was the least significant two bits of the input. The ripple carry adder takes the carry bit from the previous stage and the two inputs from the auxiliary register. The carry bit was connected directly to ground (logic 0) in the following design.

The algorithm for the decimal adjust instruction was as follows: if the carry bit (CY) or the auxiliary carry bit (AC) were set, then the result was adjusted by adding 6H (0110) to the least significant nibble (4 bits) of the result. If the carry bit (CY) or the auxiliary carry bit (AC) were set, then the result was adjusted by adding 6H (0110) to the least significant nibble (4 bits) of the result.

The main conflict between the ripple carry adder and the auxiliary register was the carry bit. The carry bit was connected directly to ground (logic 0) in the following design. The carry bit was connected to logic 0 in the following design.

And inputs S₁ corresponding to the MSN and the LSN of the auxiliary register were made to be ‘1’ whenever the carry bit and the auxiliary carry bit were ‘1’, respectively.

With this configuration, the following five outputs were possible:

Figure 1—BCD MUX Inputs and Outputs

S ₁ (MSN)	S ₁ (LSN)	S ₀	MUX Outputs
0	0	0	0000
0	0	1	0001
0	1	0	0010
0	1	1	0011
1	0	0	0100
1	0	1	0101
1	1	0	0110
1	1	1	0111

The logic circuit designed to control the S_0 inputs was simply an eight-input AND gate with four NOT gates complementing the values of IR_5 , IR_3 , IR_1 and IR_0 , as shown in Figure 2, below. Thus the state of S_0 was '1' only for the D4H instruction, as mentioned before.

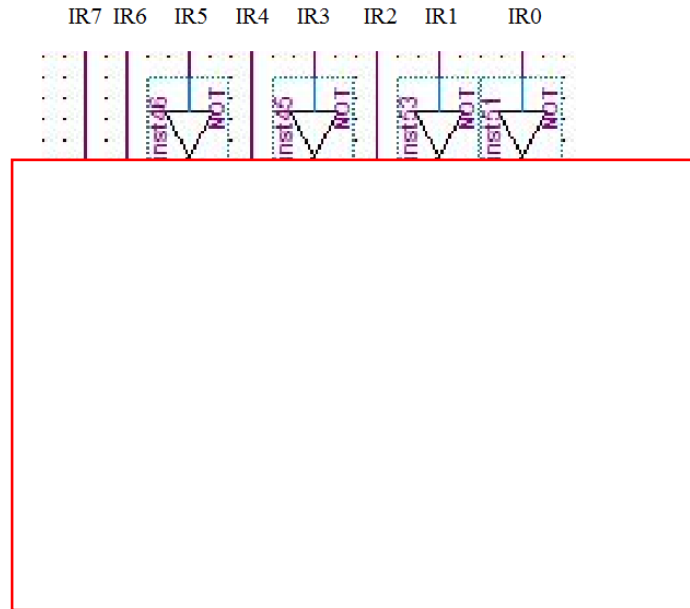


Figure 2—DA Instruction Decoding

The auxiliary carry used to control the state of the S_1 's in the LSN did not already exist in the WIMP51. This was done simply in the ripple adder, as shown in the ripple adder circuit. The carry would be latched during the p-flop circuit that was already present. In both cases, the state of the carry is determined from the IR.

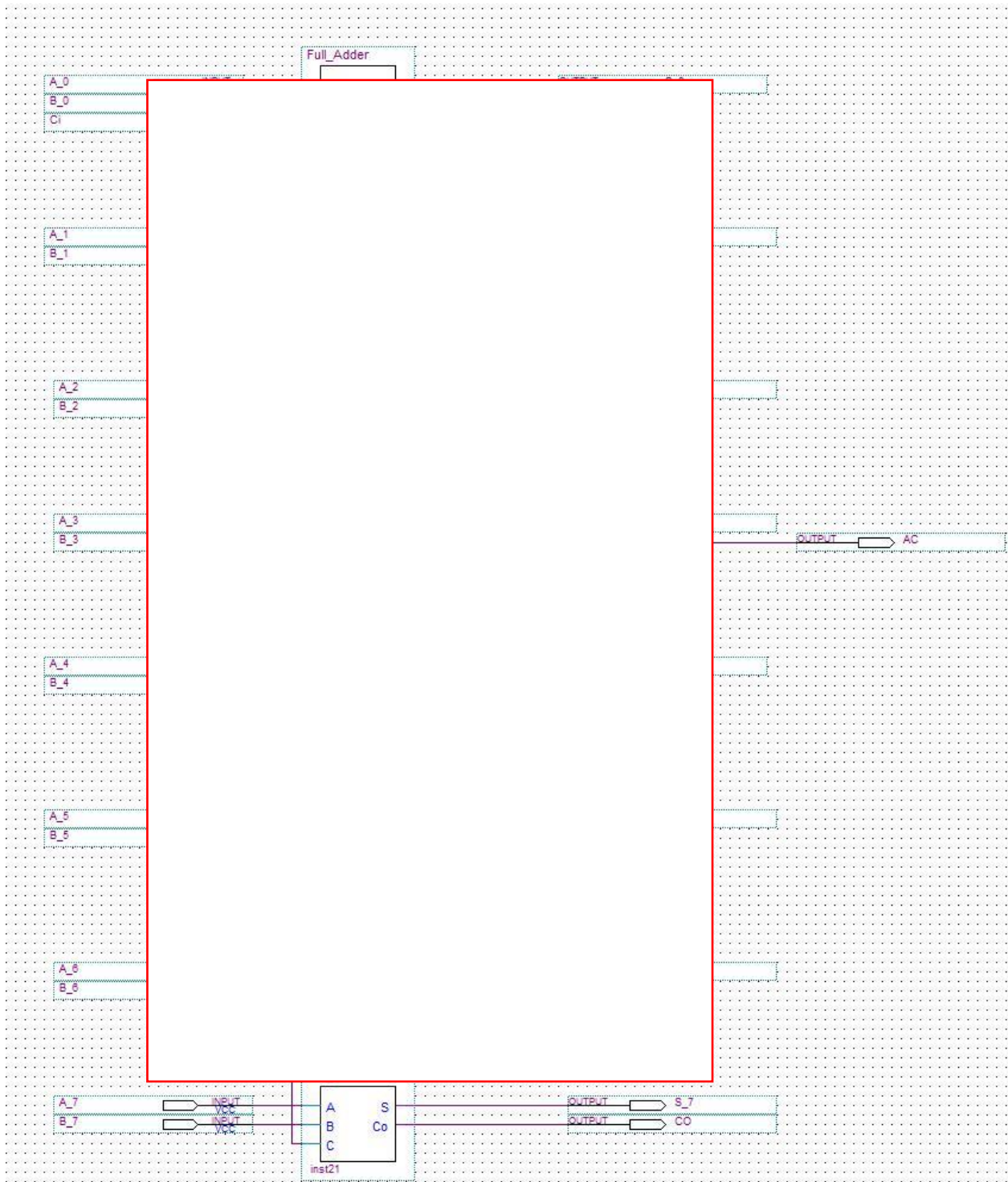


Figure 3—Auxiliary Carry

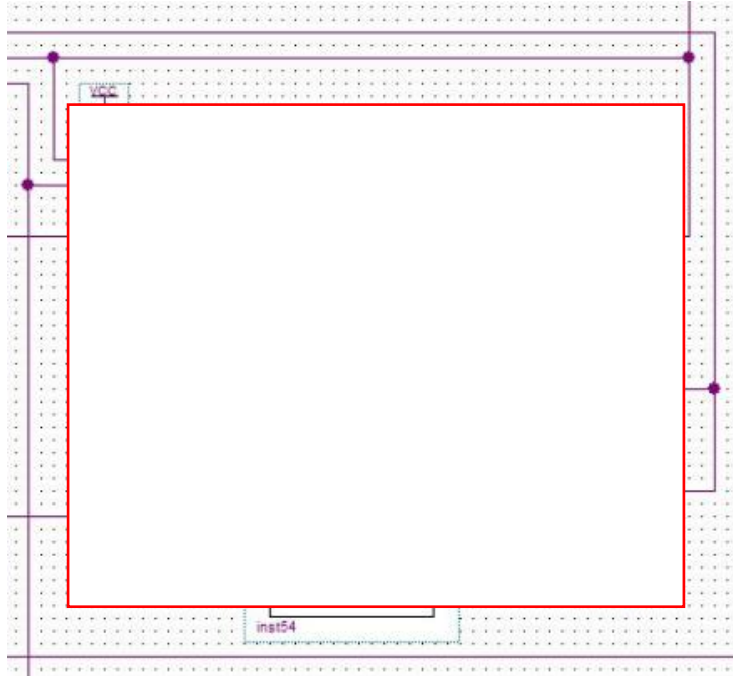


Figure 4—Latching of AC Bit

Two additional modifications were found to be necessary before DA would function properly. First, the MS (1) had to be added as a condition for accumulator write-carry bit being held in carry-in during the DA (see Figure 5). And second, the blocked from the ripple adder cause one of the conditions for DA adding 0110 to the MS to the adder carry-in in this case, then 0111 would be ac 7' instead of '6'. Figure 6 shows the 2:1 MUX inserted i ck it during DA.

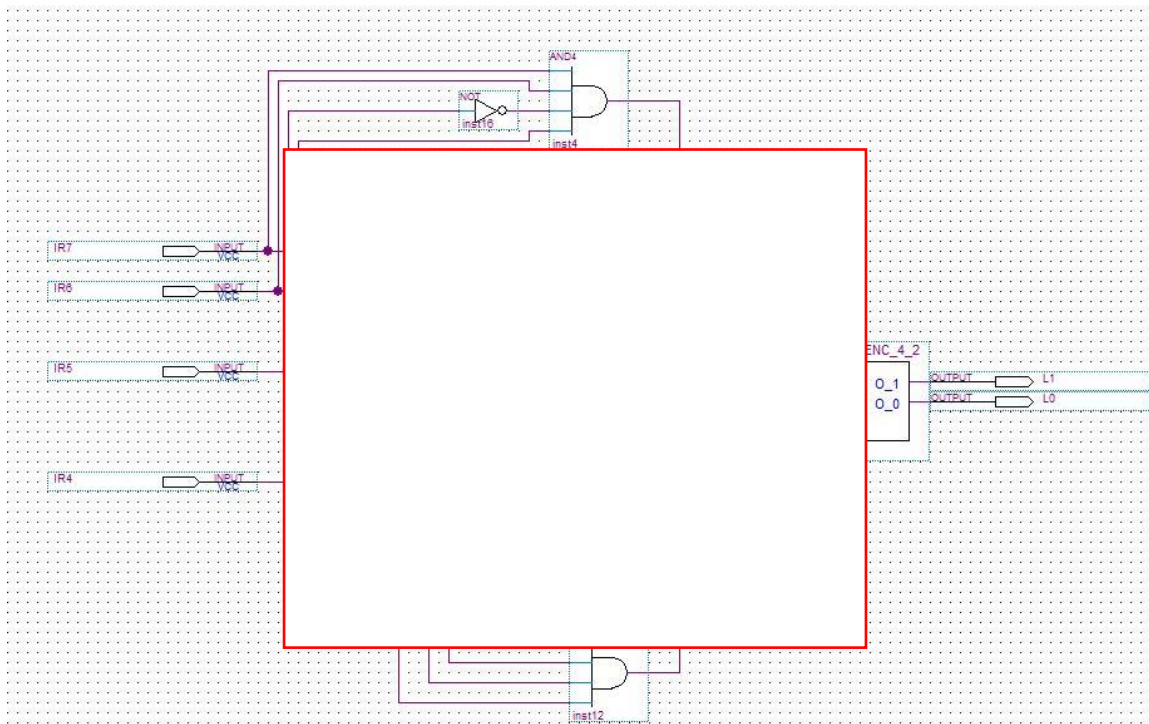


Figure 5—LA Select

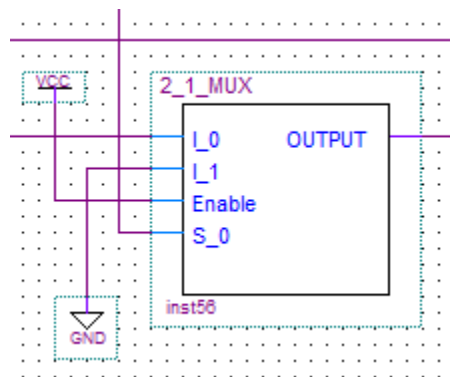


Figure 6—Block Carry-in for DA

Finally, the DA instruction, as well as the entire standard WIMP51 instruction set, was tested to ensure that everything was working properly. The test code used can be found in Appendix A. Lines 00-1B of this program demonstrate the functionality of the DA instruction, and line 1B-38 make us of all of the other instructions.

Conclusion

As mentioned above, the problem seemed simple enough—the problem of how to implement BCD arithmetic in WIMP51. Still, some trial and error proved necessary before a fully functioning solution was found. However, such unforeseen difficulties cannot help but further the learning process.

Appendix A—Test Program

	Code		Accumulator	Notes
00	CLR C	C3H	00H	
01	MOV A, #00H	74H	00H	
02		00H	00H	
03	ADDC A, #0AH	34H	00H	
04		0AH	00H	
05	DA A	D4H	0AH	LSN>9
06	ADDC A, #F0H	34H	10H	
07		F0H	10H	
08	DA A	D4H	00H	C=1
09	CLR C	C3H	60H	
0A	ADDC A, #60	34H	60H	
0B		60H	60H	
0C	DA A	D4H	C0H	MSN>9
0D	CLR C	C3H	20H	
0E	SWAP A	C4H	20H	
0F	ADDC A, #0F	34H	02H	
10		0FH	02H	
11	DA A	D4H	11H	AC=1
12	CLR C	C3H	17H	
13	ADDC A, #FB	34H	17H	
14		FBH	17H	
15	DA A	D4H	12H	C=AC=1
16	CLR C	C3H	78H	
17	ADDC A, #44	34H	78H	
18		44H	78H	
19	DA A	D4H	BCH	MSN, LSN>9
1A	CLR C	C3H	22H	
1B	DA A	D4H	22H	MSN, LSN<9, C=AC=0
1C	MOV A, #05H	74H	22H	
1D		05H	22H	
1E	ADDC A, #07H	34H	05H	
1F		07H	05H	
20	MOV R7, A	FFH	0CH	
21	ADDC A, R7	3FH	0CH	
22	SWAP A	C4H	18H	
23	MOV A, R7	EFH	81H	
24	XRL A, R7	6FH	0CH	
25	ORL A, R7	4FH	00H	
26	SWAP A	C4H	0CH	
27	ADDC A, R7	3FH	C0H	
28	ANL A, R7	5FH	CCH	
29	SETB C	D3H	0CH	
2A	CLR C	C3H	0CH	

2B		MOV A, #04H	74H	0CH
C2			04H	0CH
2D	X:	CLR C	C3H	04H
2E		ADDC A, #FFH	34H	04H
2F			FFH	04H
30		JZ Y	60H	03H, 02H, 01H, 00H
31			02H	
32		SJMP X	80H	
33			F9H	
34	Y:	SETB C	D3H	00H
35		ADDC A, #02H	34H	00H
36			02H	00H
37	Z:	SJMP Z	80H	03H
38			FEH	03H