

Litany For Energy Problems [©2012 RJ Bieniek]

1. A detailed sketch of the physical elements of the problem with all relevant positions clearly labeled for all states (e.g., initial and final). For example, in a gravitational problem involving two objects, the initial and final y **should** be shown for **each** particle with full subscripts uniquely identifying them: $y_{1i}, y_{1f}, y_{2i}, y_{2f}$, and the $y=0$ level (Note: “**should**” \approx “**must**”). Some of these can be added as you solve the problem, but a diagram comes first even if it is initially incomplete.
2. **A fundamental equation must appear**, e.g., $E_f - E_i = (W_{\text{other}})_{i \rightarrow f}$.
3. Write an expression for mechanical energy where kinetic energies of all particles in the system and each of the potential energies due to conservative forces are identified. For example, if gravity and a spring act on a single particle, one writes $E = K + U_g + U_s$ or $E = \frac{1}{2}mv^2 + mgy + \frac{1}{2}ks^2$. Include the work done by OTHER forces in W_{other} . If no other force acts except those already accounted for in potential energy, $(W_{\text{other}})_{i \rightarrow f}$ can be zeroed out. **But check and verify your decisions!**
4. If more than one potential acts (e.g., gravity and a spring), each potential **should** appear on **both** sides of the equation. Write out the explicit mathematical form for the potentials, with appropriate initial or final subscripts, e.g., mgy_i for the initial gravitational potential energy. **When you use such position-dependent formulae, you must clearly include the initial and final position symbols in your diagram (preferably with their value, e.g., $y_i = +H$ and $s_f = -d$), along with the location of the reference zero value, e.g., $y=0$.**

For example, consider the initial state of a particle at rest that is to be launched from a spring of compression d at a vertical distance h below the $y=0$ level in a gravitational field, the following steps **should** appear:

$$E_i = E_f \quad \text{because } (W_{\text{other}})_{i \rightarrow f} = 0$$

$$K_i + (U_g)_i + (U_s)_i = \text{analogous final-state expression}$$

$$\frac{1}{2}m \cancel{v}_i^2 + mgy_i + \frac{1}{2}ks_i^2 = \text{analogous final-state expression}$$

$$mg(-h) + \frac{1}{2}k(-d)^2 = \text{analogous final-state expression}$$

5. After they appear in your diagram, go ahead and substitute the algebraic values shown into your mathematics. Do not zero out a term unless your diagram supports it!

As an example, consider an Atwood machine with $M > m$ and a massless pulley. Block M starts from rest and falls onto a spring (spring constant k), from an initial height h above it. When M is released, block m is pulled upward by an additional external force whose magnitude P equals half the block’s weight magnitude. What is the spring’s maximum compression d ?

$$E_f - E_i = (W_{\text{other}})_{i \rightarrow f} \Rightarrow E_f = E_i + (W_P)_{i \rightarrow f}$$

$$\frac{1}{2}M \cancel{v}_f^2 + \frac{1}{2}m \cancel{v}_f^2 + [Mg Y_f + mg y_f + \frac{1}{2}k s_f^2]$$

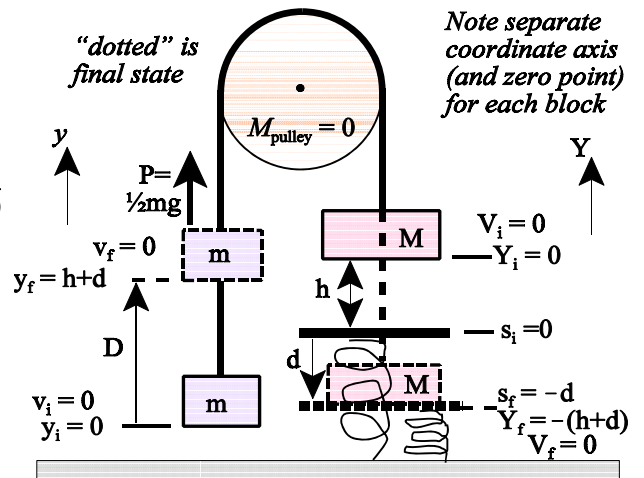
$$= \frac{1}{2}M \cancel{v}_i^2 + \frac{1}{2}m \cancel{v}_i^2 + [Mg Y_i + mg y_i + \frac{1}{2}k s_i^2] + \vec{P} \cdot \vec{D}$$

$$Mg[-(h+d)] + mg[+(h+d)] + \frac{1}{2}k(-d)^2 = +PD$$

$$-Mg(h+d) + mg(h+d) + \frac{1}{2}kd^2 = (\frac{1}{2}mg)(h+d)$$

$$[\frac{1}{2}k]d^2 + (\frac{1}{2}m - M)gd + (\frac{1}{2}m - M)gh = 0$$

Solve this quadratic equation for d !



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